

Chemical Robotics in Medicine: Components, Perspectives and Applications

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*Centralizovaný rozvojový projekt MŠMT č. C29:
„Integrovaný systém vzdělávání v oblasti výskytu a eliminace reziduí léčiv v životním prostředí“*

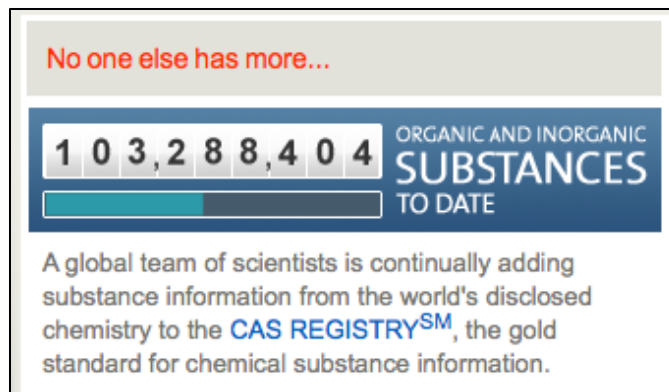


Motivation and Aims

How many molecules are known to mankind?



Source: www.cas.org



How many of them are FDA-approved drugs?



Statistics	
Drug Statistics	
Total Number of Small Molecule Drugs	7451
Total Number of Biotech Drugs	289
Total Number of Approved Drugs	1741

Total Number of Approved Drugs 1741

Total Number of Experimental Drugs	5064
Total Number of Illicit Drugs	186
Total Number of Withdrawn Drugs	163
Total Number of Drugs	7740

Motivation and Aims

1,741 : 89,578,080 \approx 1 : 50,000

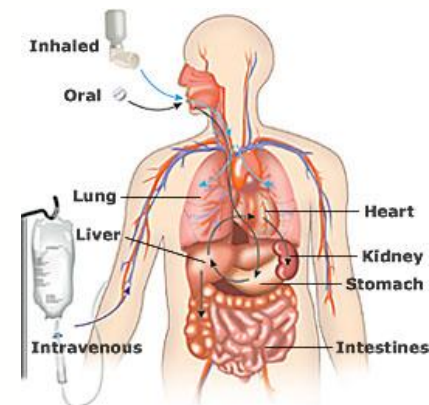
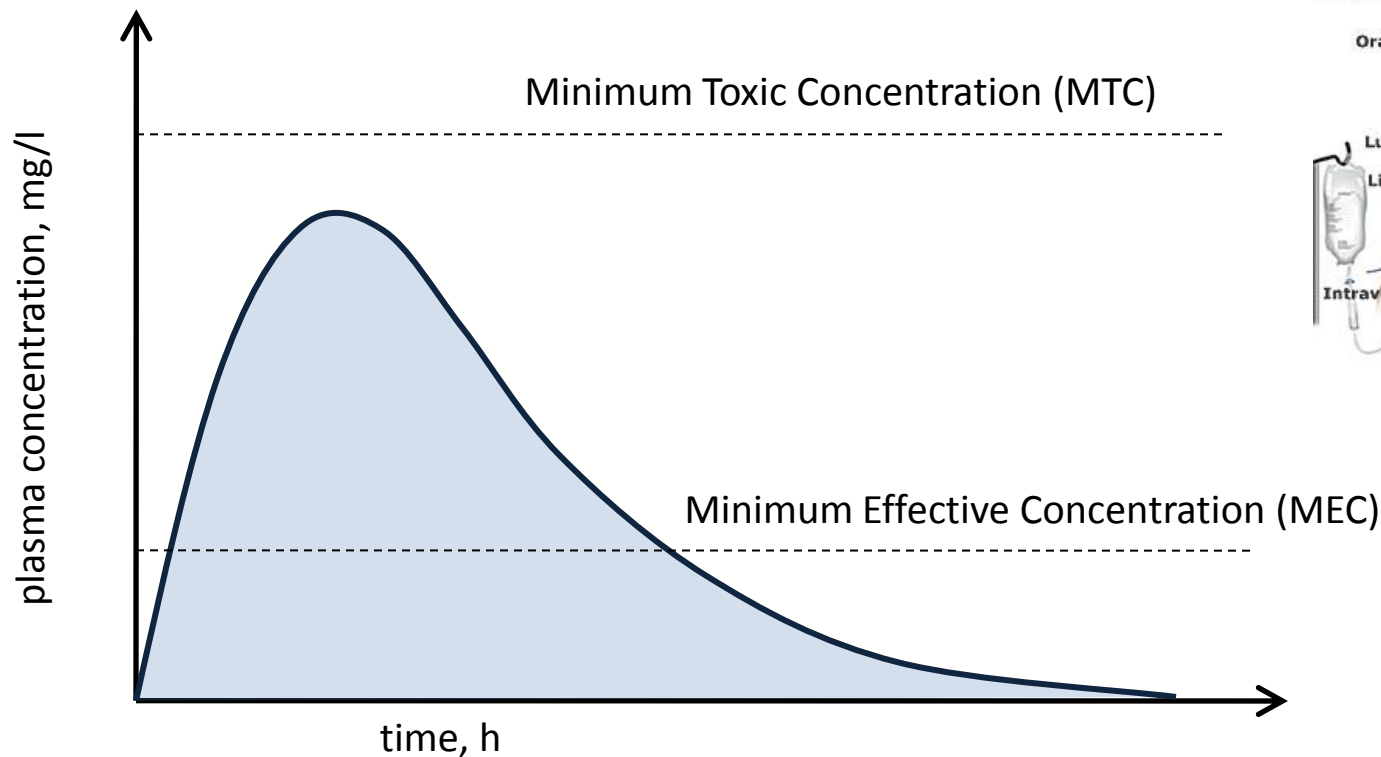
Why?

1. Low/insufficient potency
2. Too high potency/toxicity
3. Unsuitable for established manufacturing, formulation and supply chain paradigms



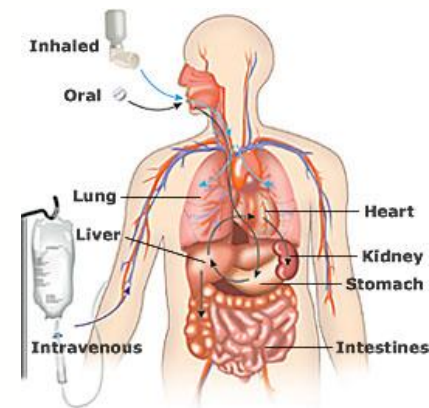
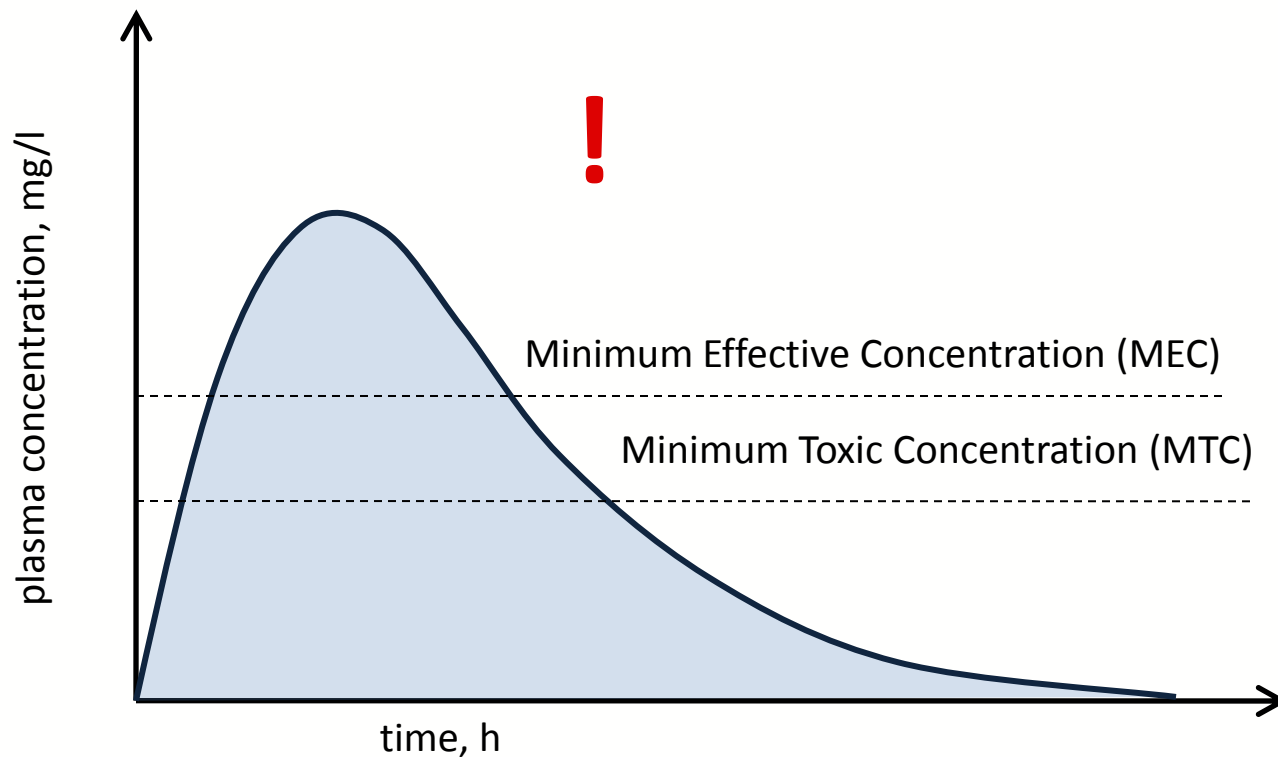
Problem of high potency

Pharmacokinetic profile – single dose response



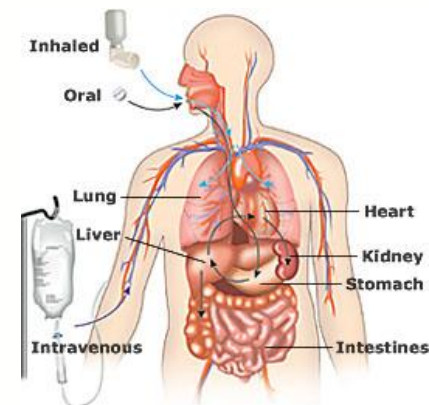
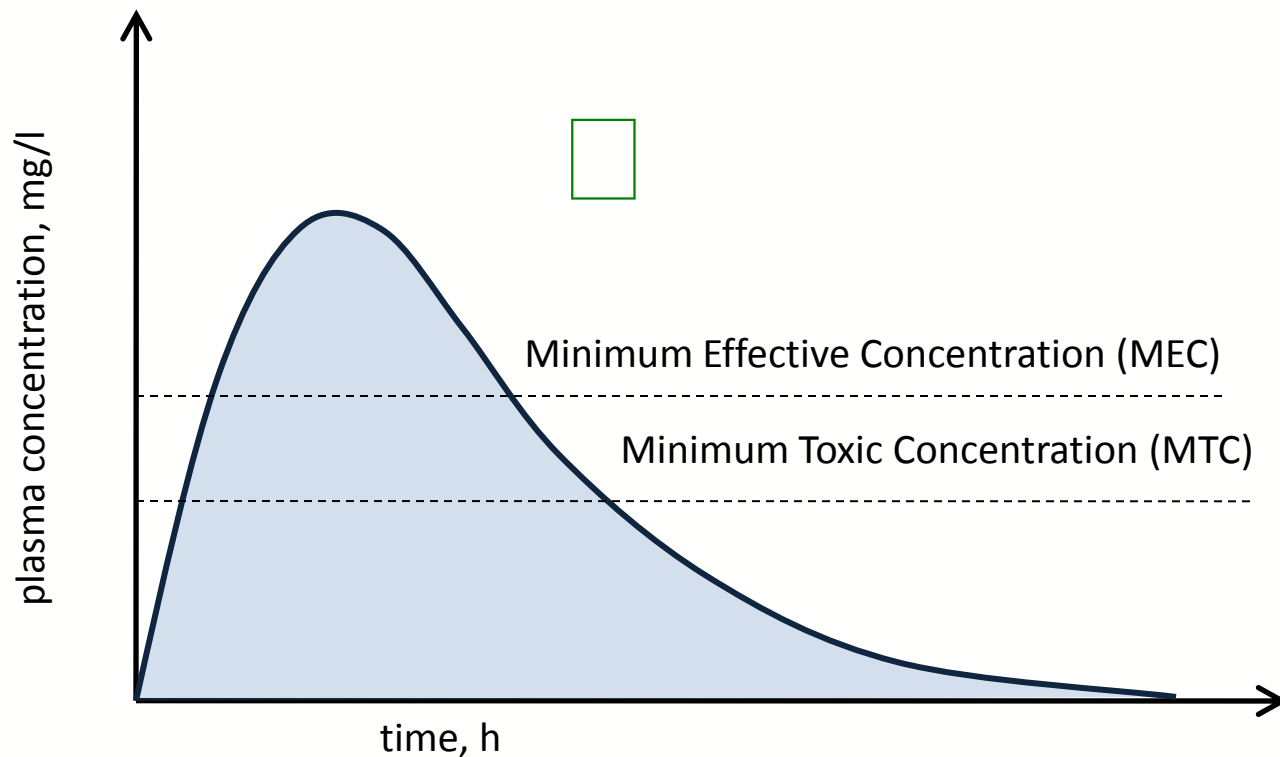
Problem of high potency

Problem: systemic application of pre-existing API

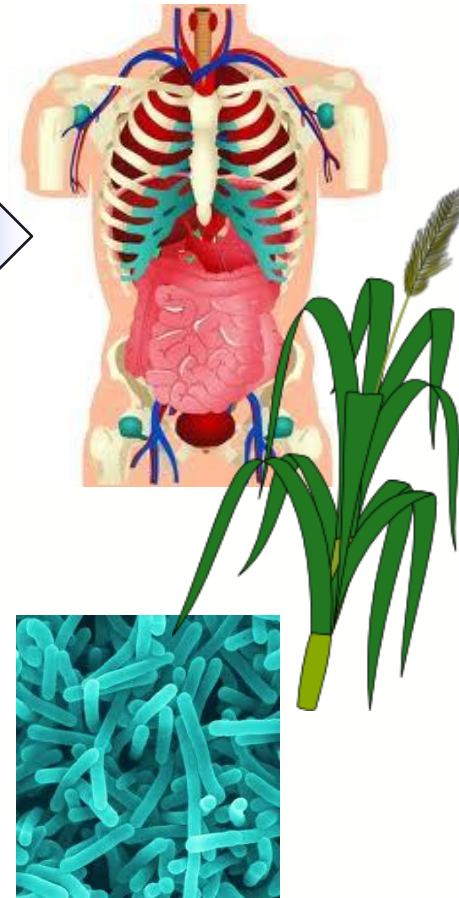
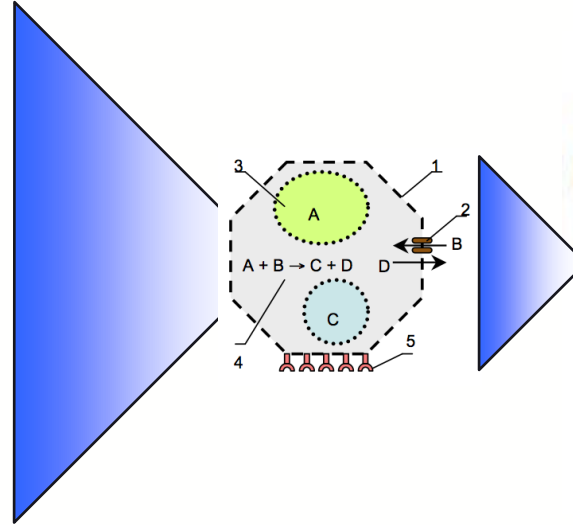


Problem of high potency

Possible approach: local, in-situ production of API



In-particle production of API

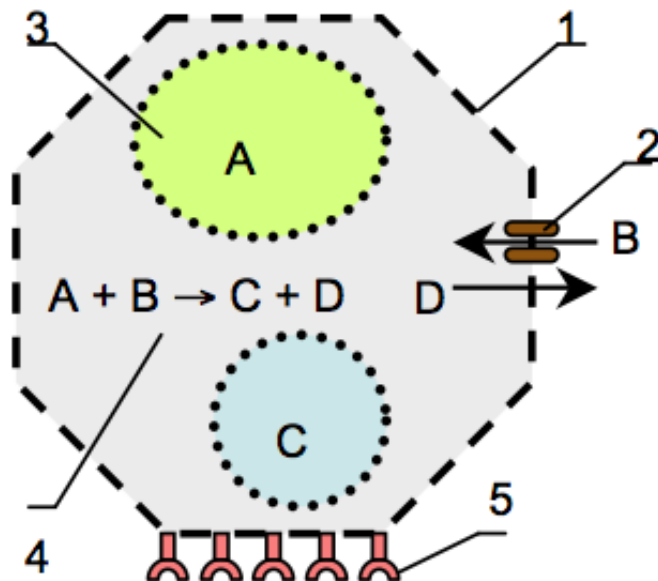


Engineering challenges

- 1) Design and synthesis of structured microparticles („embodiment“)
- 2) Control of local reaction-diffusion process
- 3) Control of particle transport/desposition

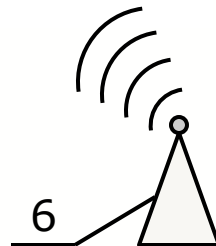
Design of a chemical microrobot

Chemical robot = Internally structured functional particle



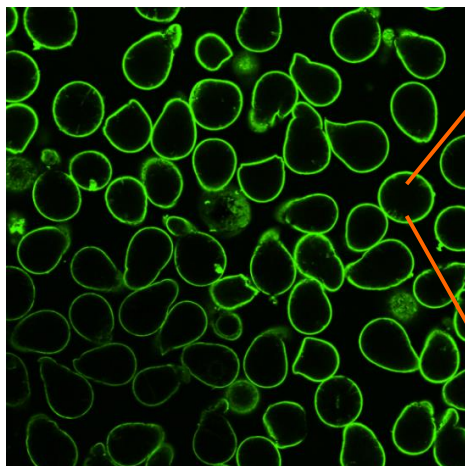
Structural and functional sub-systems:

1. Semi-permeable shell (**integrity**)
2. Variable diffusion rate (**transport**)
3. Internal reservoirs (**storage**)
4. Chemical **reaction** "on-demand"
5. Surface functionalisation (**adhesion**)
6. Remote control (**communication**)

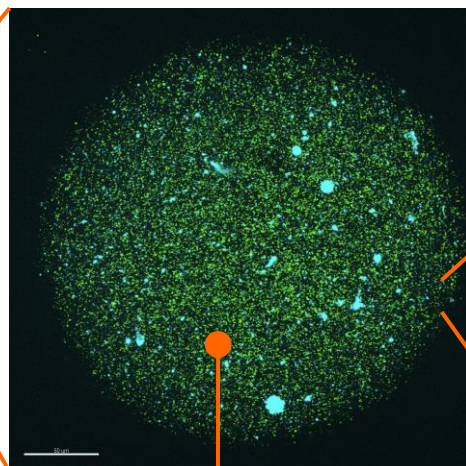


Modularity!!!

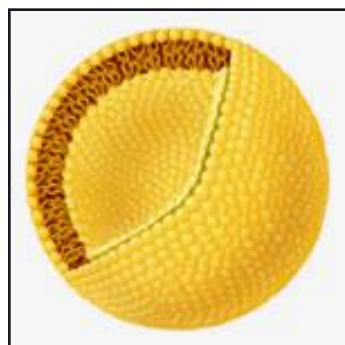
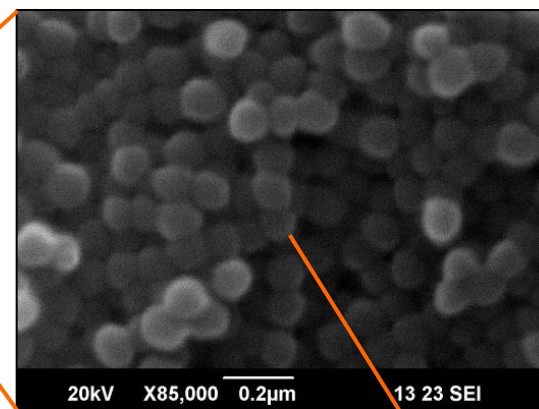
Physical implementation



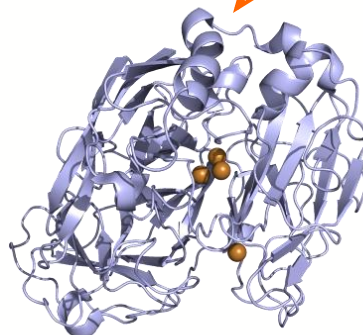
Core-shell hydrogel microparticles



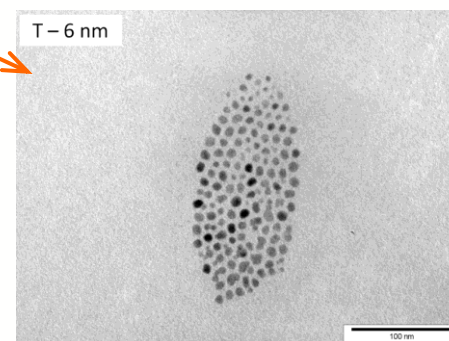
Mesoporous SiO₂ shell
(sol-gel or LbL assembly)



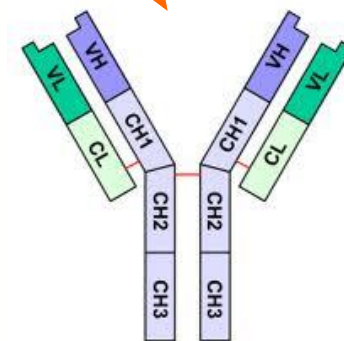
Storage vesicles
(reversible, step
change of diffusion)



Hydrogel with
immobilised
enzymes



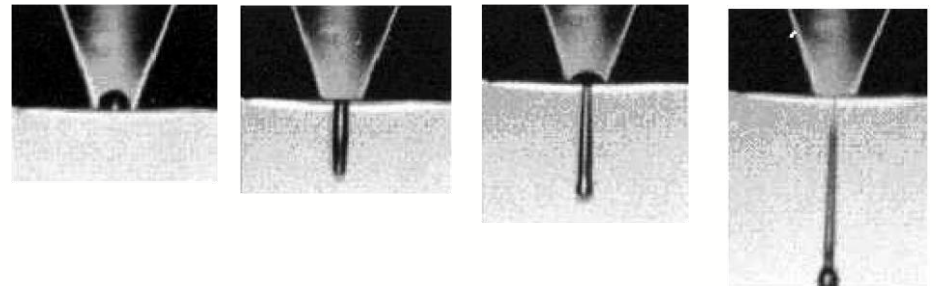
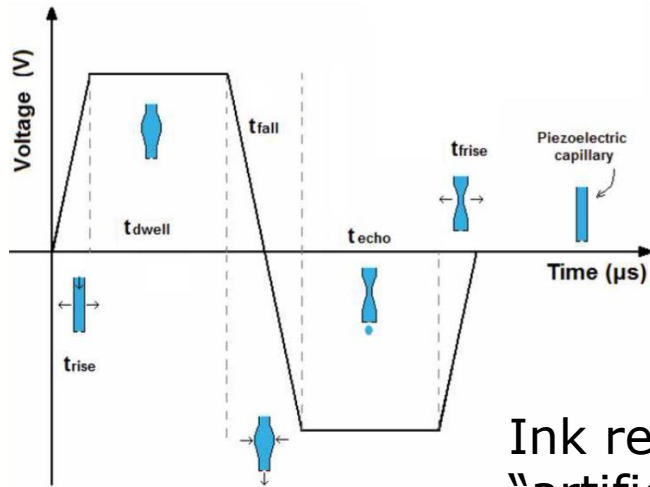
Radiofrequency
responsive
nanoparticles



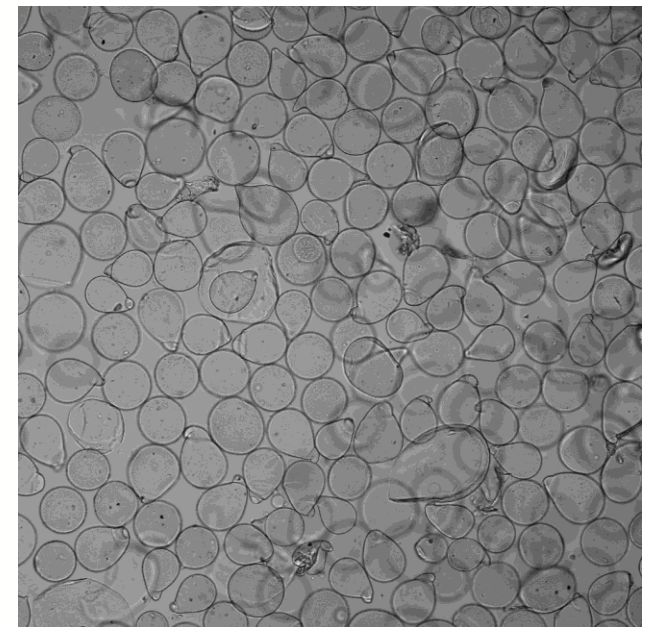
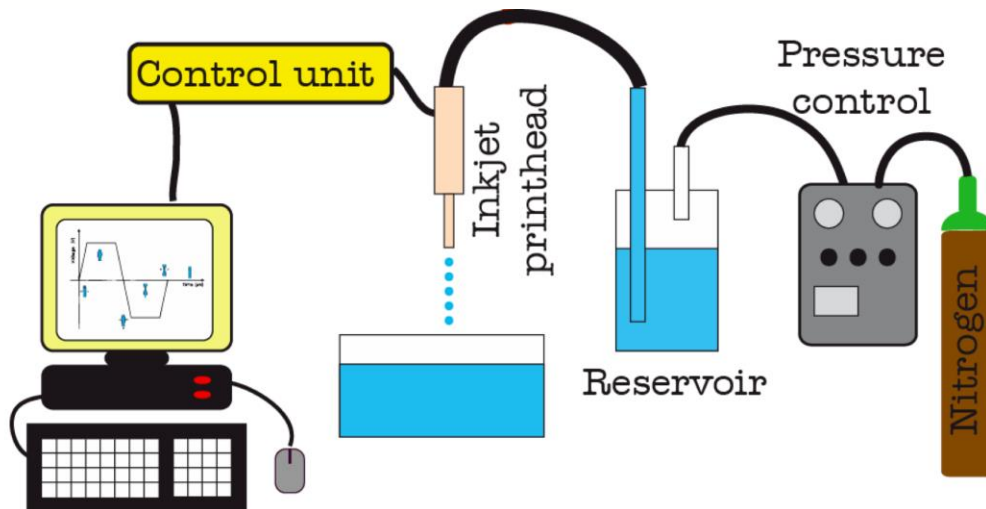
Covalently
coupled
antibody

1. Embodiment

Drop-on-Demand inkjet printing (MicroFab Inc.)

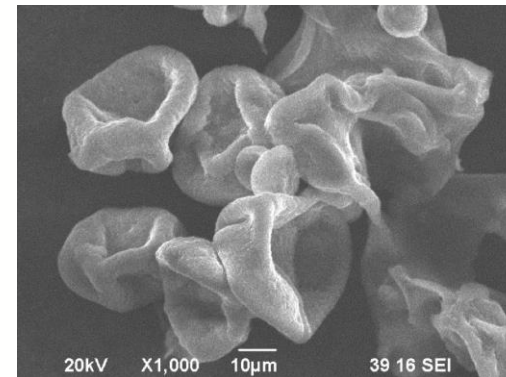
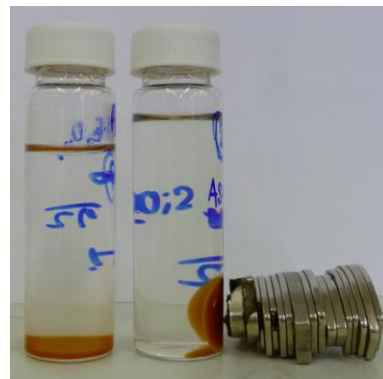
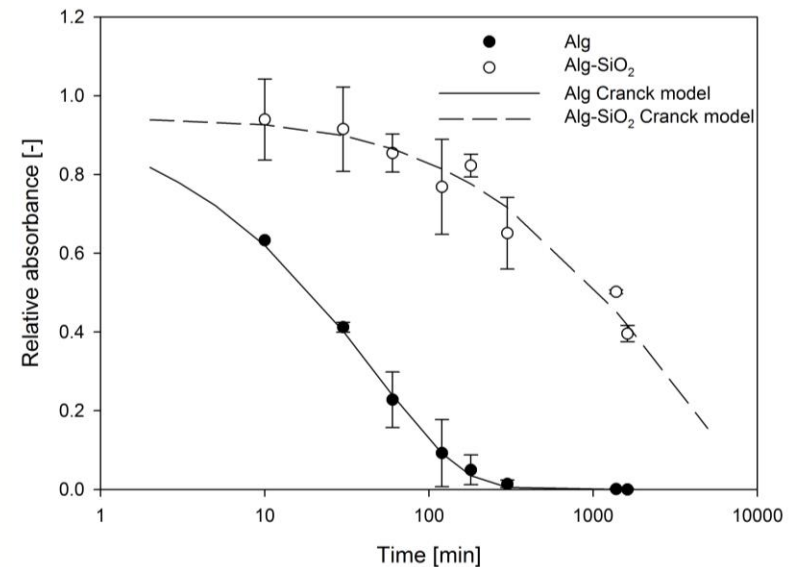
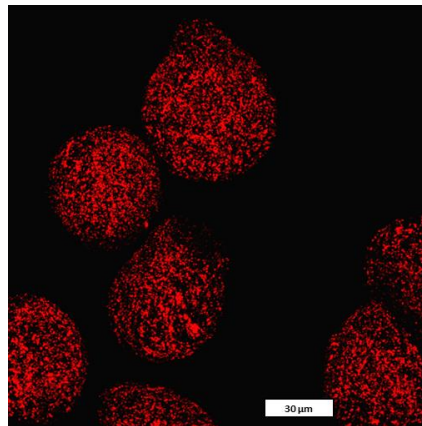
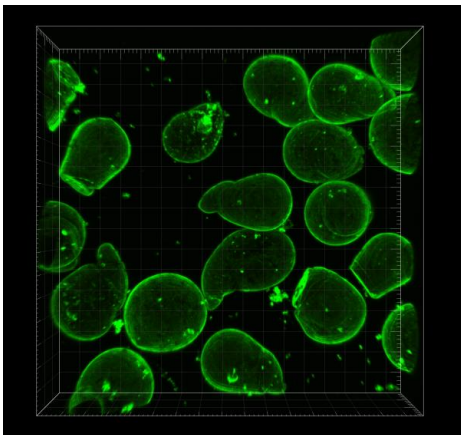


Ink replaced by
"artificial cytoplasm"

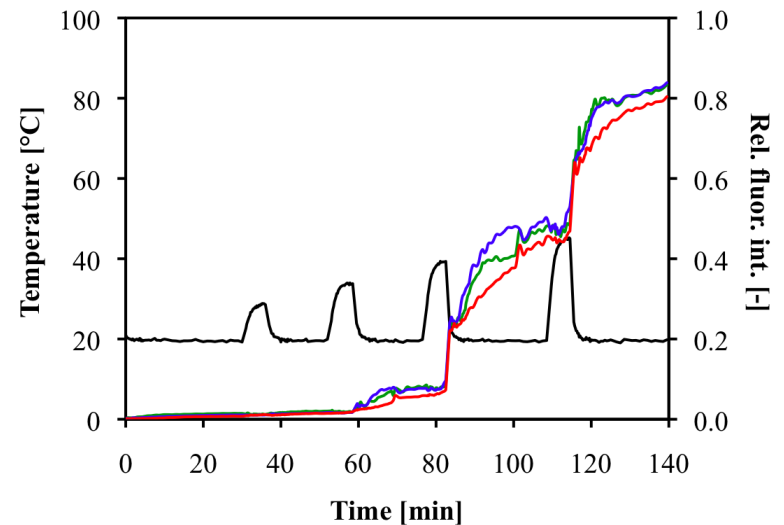
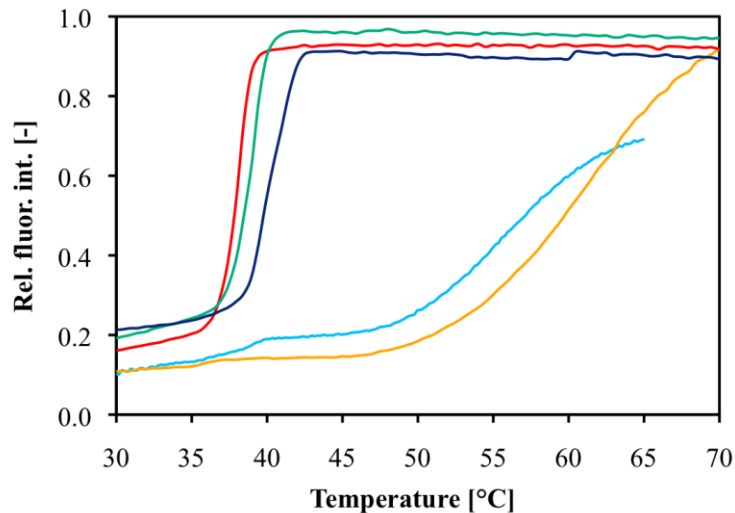
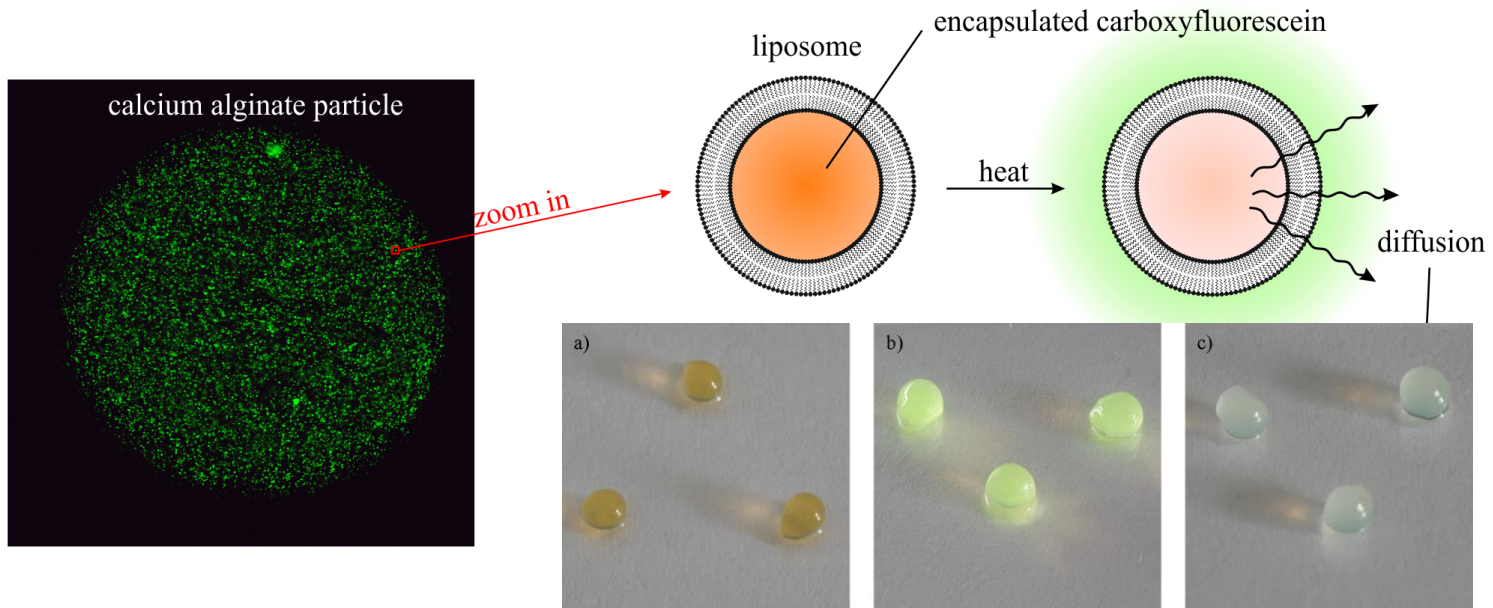


1. Embodiment

- Sol-gel or LbL (layer-by-layer) deposition process
- SiO₂ layer is flexible but improves chemical and mechanical stability
- Prevents leakage of internal components and allows surface functionalisation

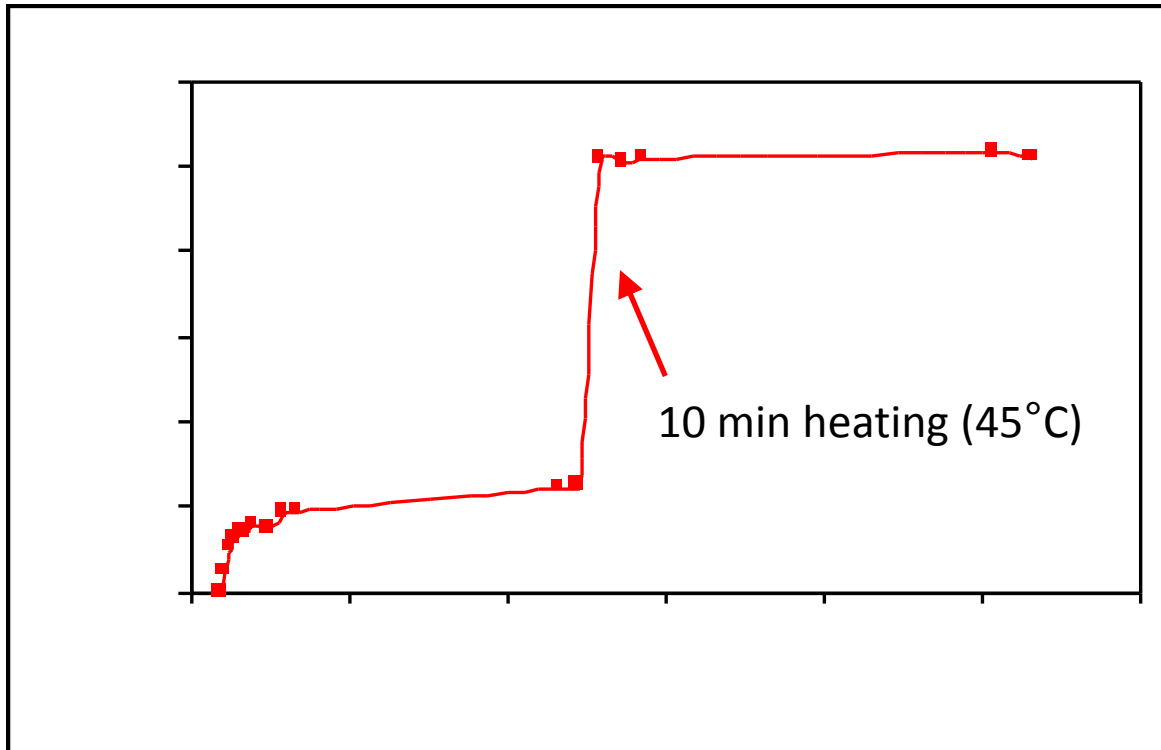
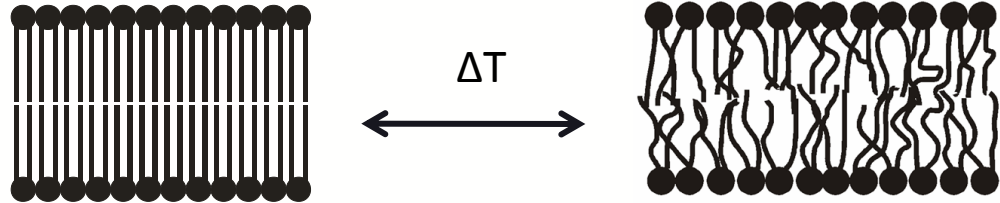


2. Storage and Release

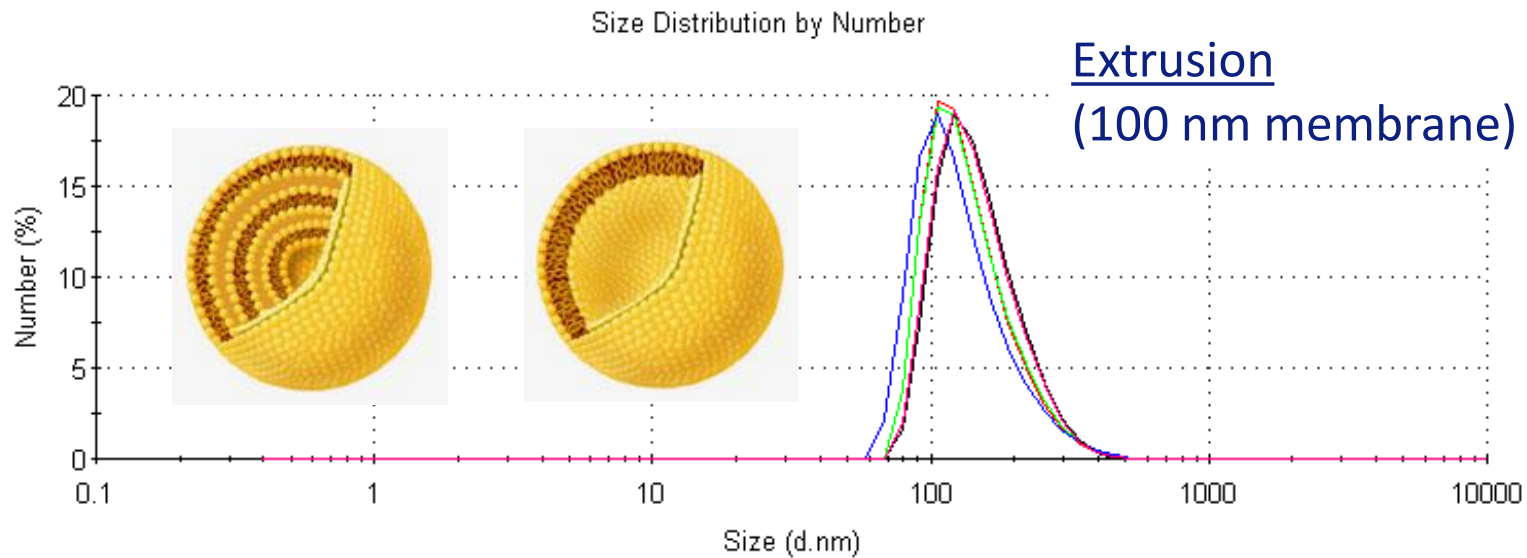
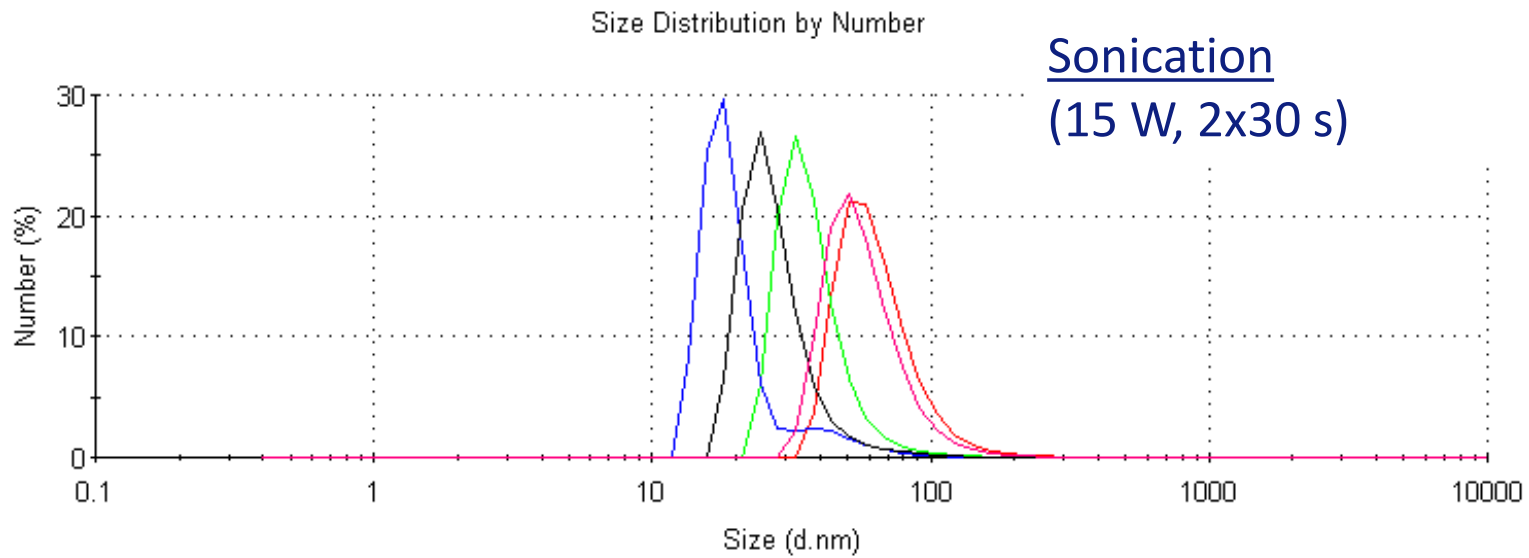


2. Storage and Release

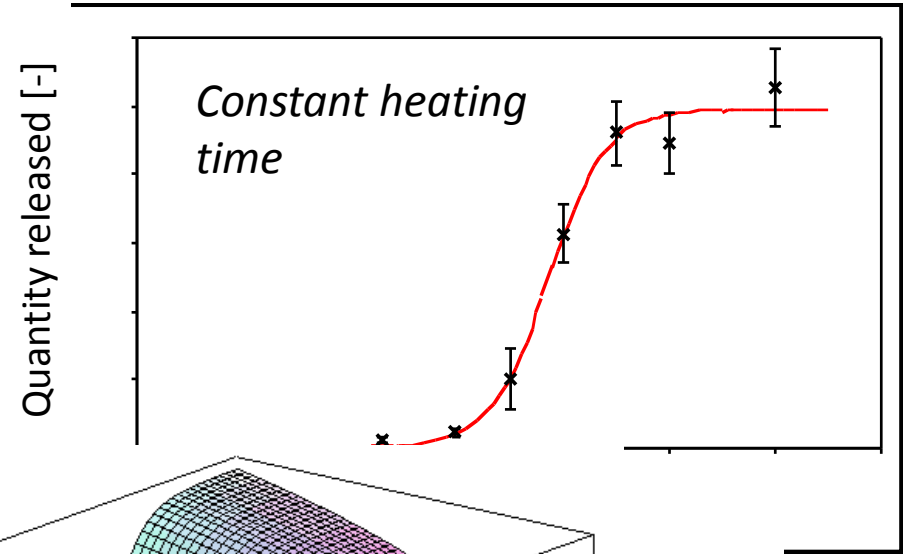
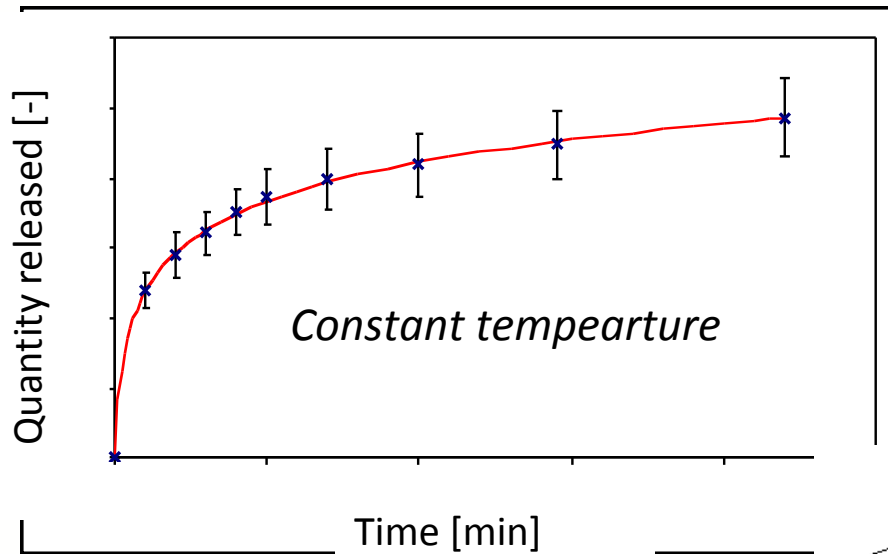
Phospholipid bi-layer



2. Storage and Release

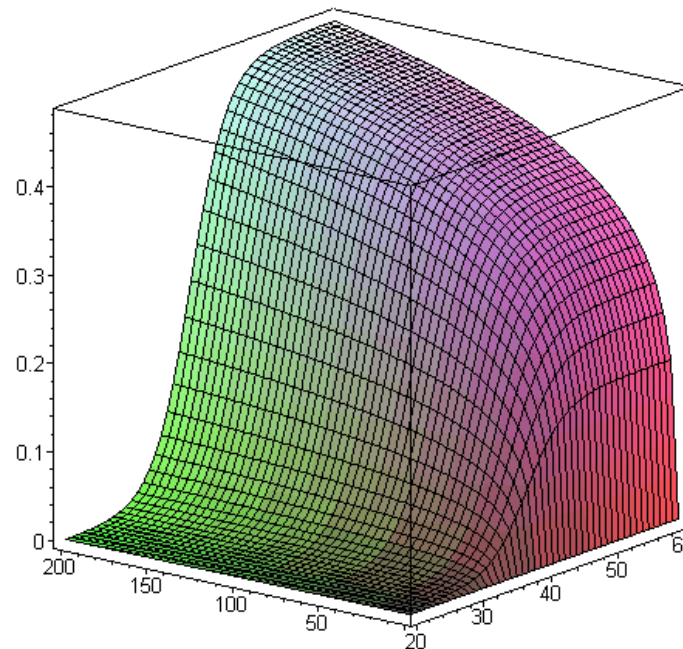


2. Storage and Release



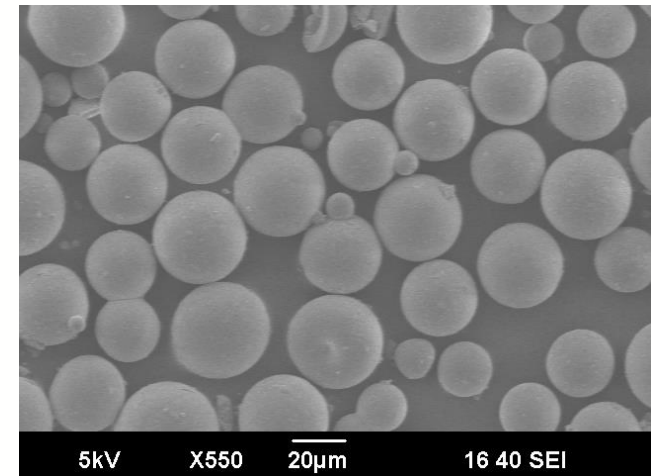
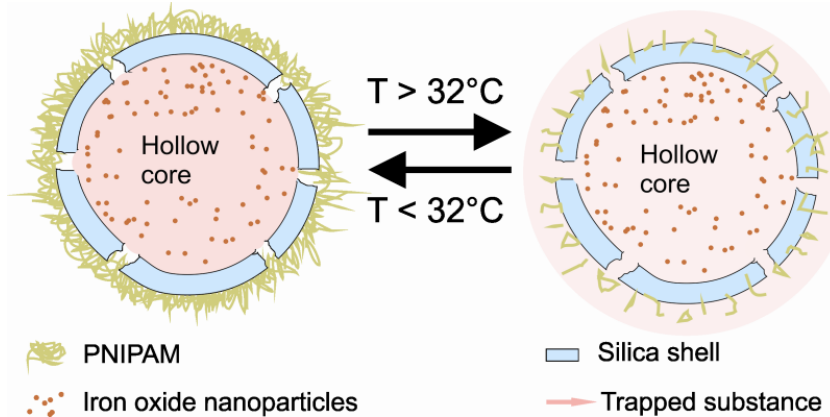
Parametric **response surface** is the basis for diffusion control

$$I_{rel}(t,T) = \frac{0,08129 \ln(1,794t+1)}{1 + e^{-0,3676(T-38,59)}}$$

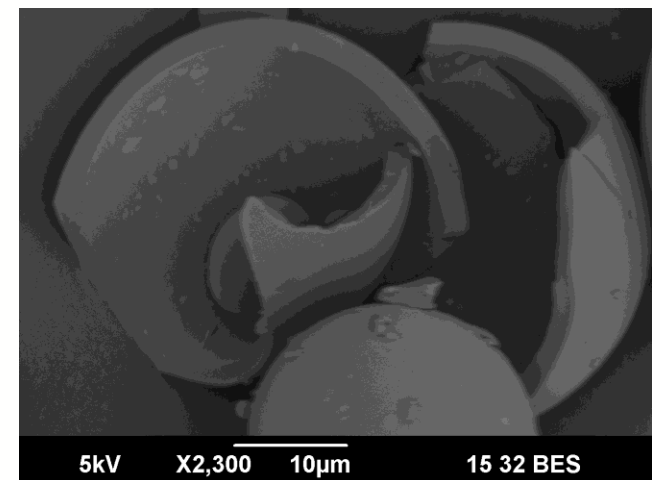
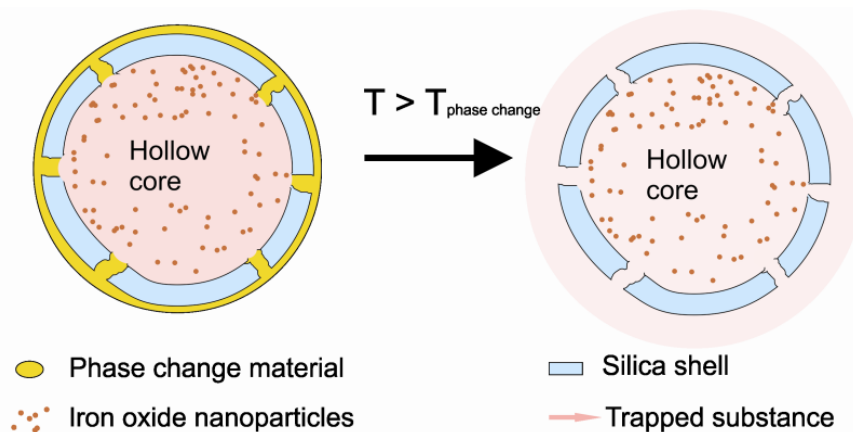


2b. Storage and Release – other mechanisms

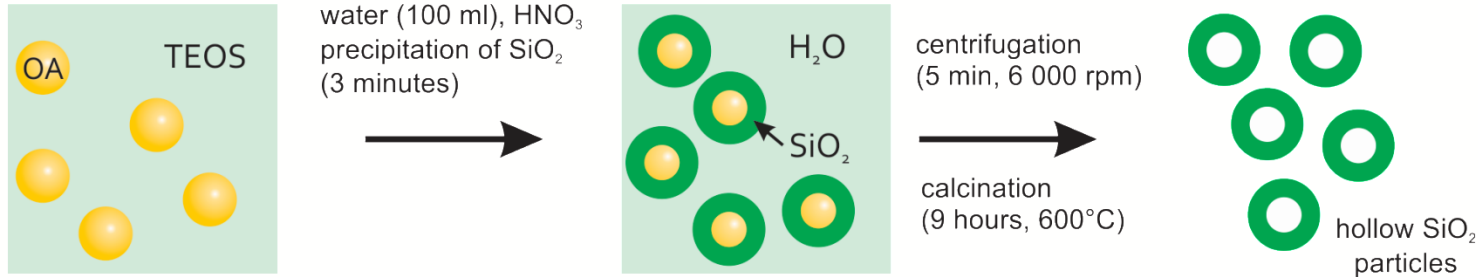
Gating effect using grafted polymer brushes



Gating effect using a phase change material



2b. Storage and Release – other mechanisms

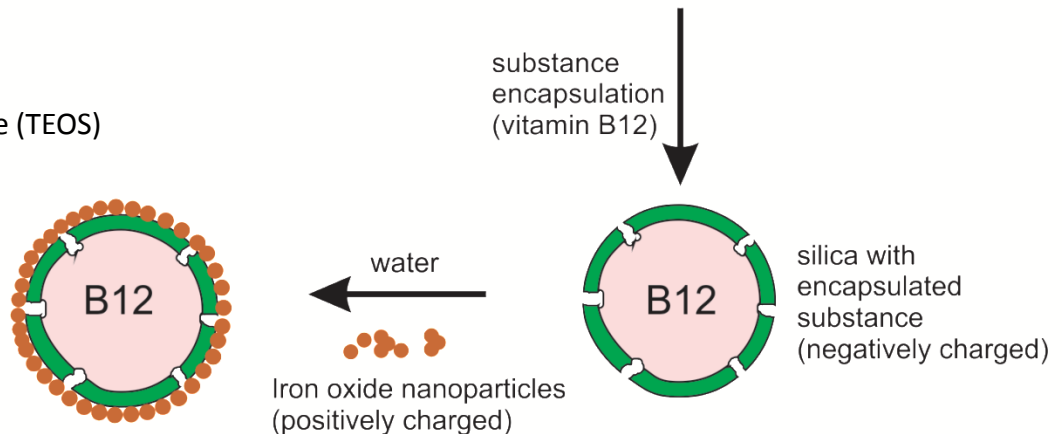
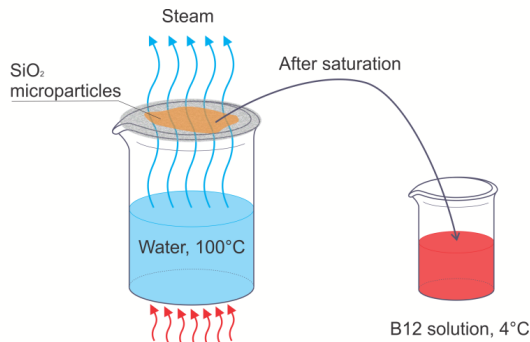


- **Soft templating method**

- Silica precursor – tetraethyl orthosilicate (TEOS)
- Liquid templates – octylamine (OA)

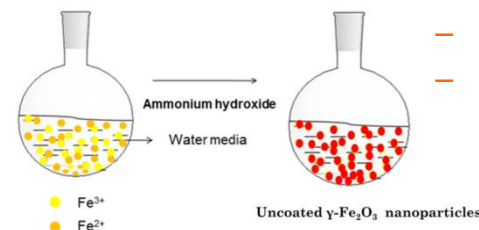
- **Substance encapsulation**

- Using hot water vapour to displace the air contained in the hollow core
- Pressure difference across the shell

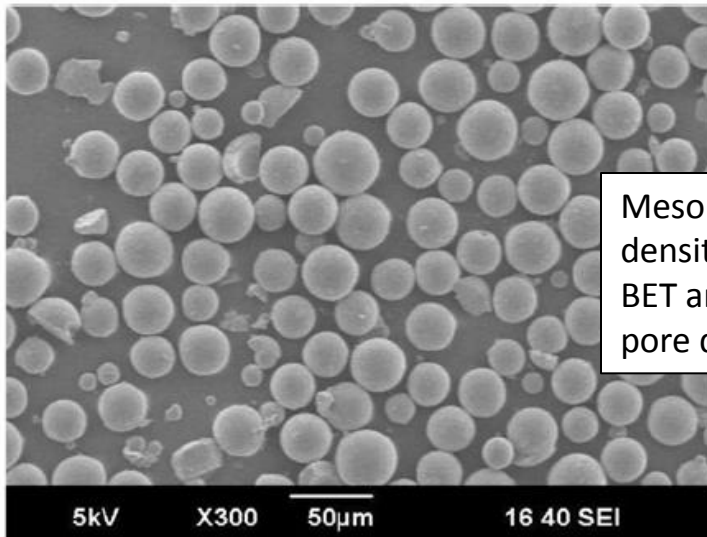


- **Superparamagnetic iron oxide nanoparticles**

- Co-precipitation method
- $\text{Fe}^{2+} + 2 \text{Fe}^{3+} + 8 \text{OH}^- \rightarrow \text{Fe}_3\text{O}_4 + 4 \text{H}_2\text{O}$

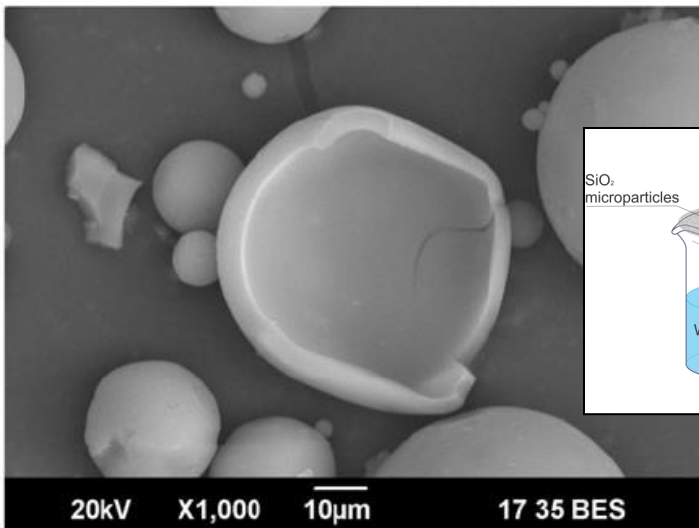
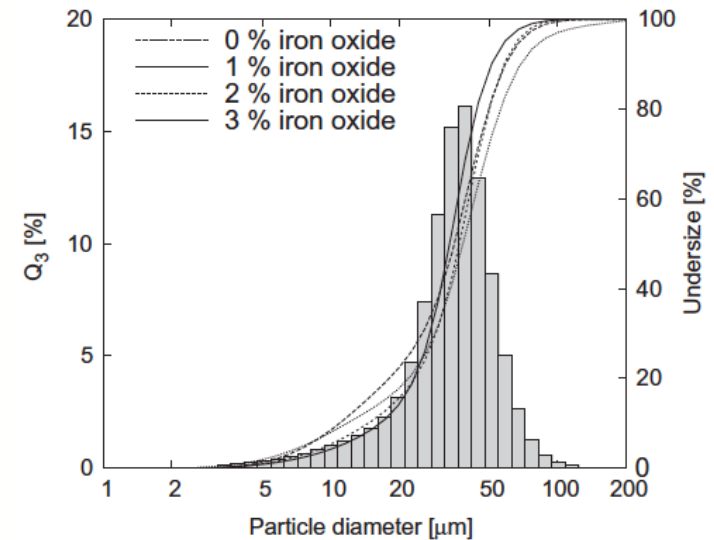


2b. Storage and Release – other mechanisms

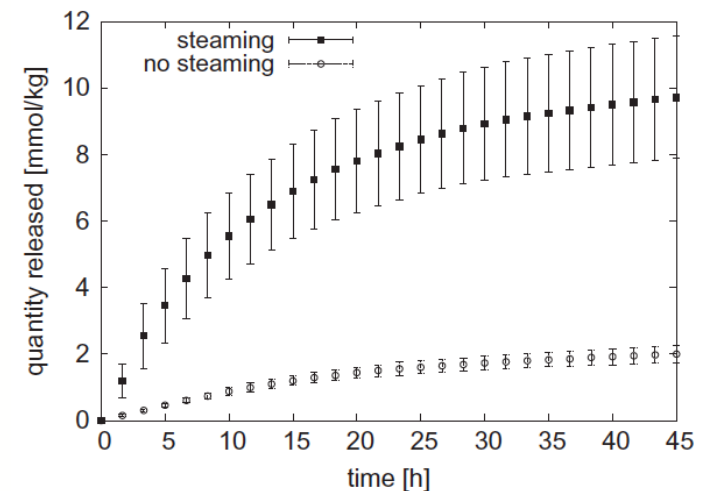
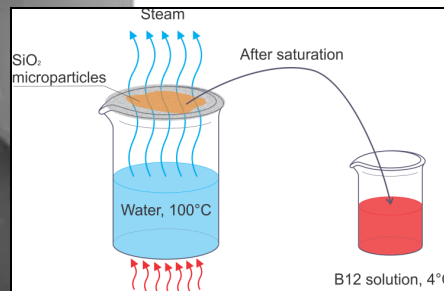


Size distribution

Mesoporous SiO₂ shell:
density 2.095 g/cm³
BET area 834.6 m²/g
pore diameter 6.03 nm

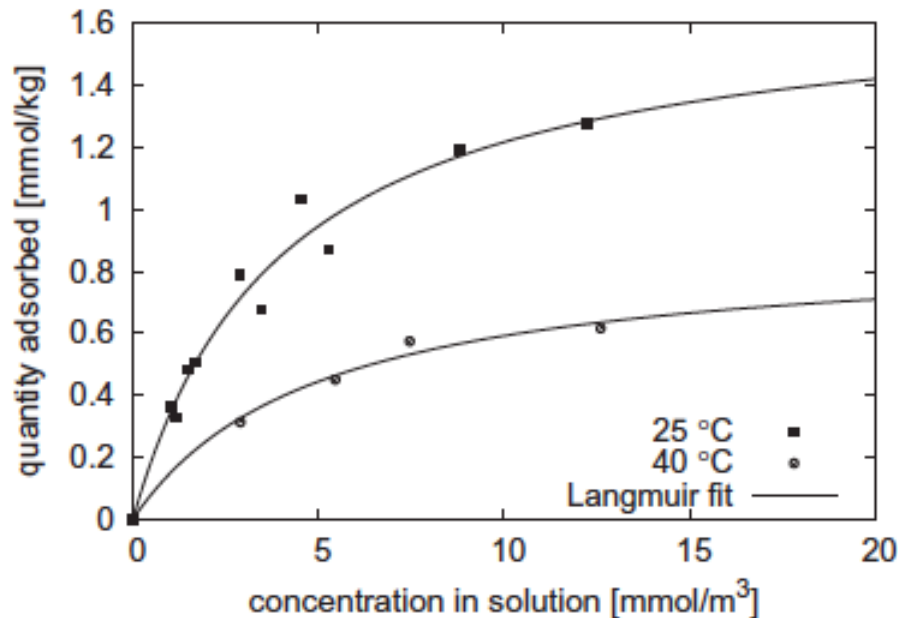


Particle loading

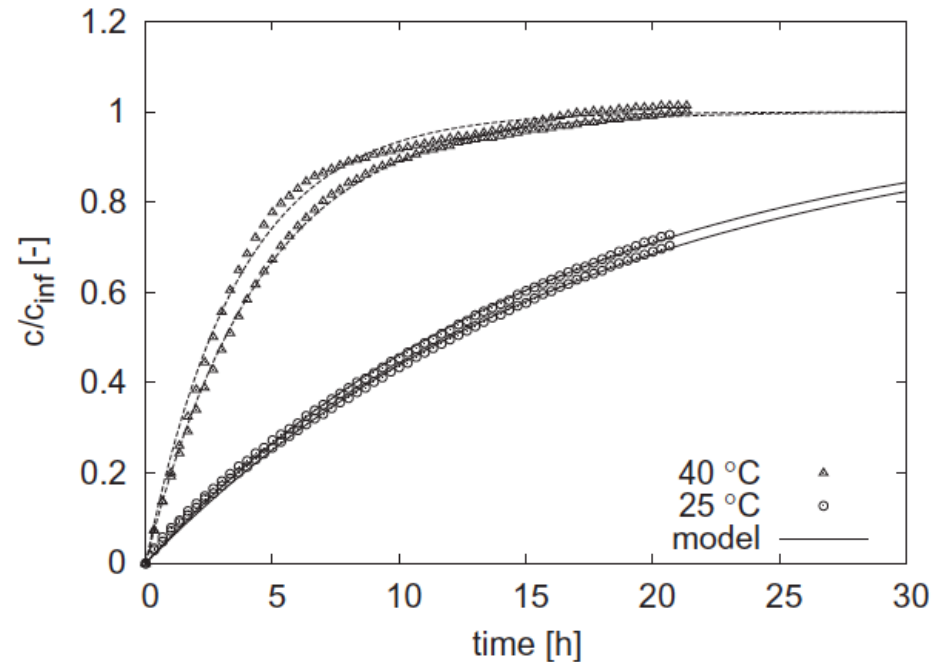


2b. Storage and Release – other mechanisms

Adsorption equilibrium $q = q_m \frac{K_a c}{1 + K_a c}$



Diffusion model $c(t) = c_{\infty}(1 - \exp(-\beta t))$



$$\frac{d\Delta c}{dt} = -A \frac{D_{\text{eff}}}{\delta} \Delta c \left(\frac{1}{V_p} + \frac{1}{V_{\text{out}}} \right)$$

$$V_p = V_c + \epsilon V_s + (1 - \epsilon) V_s \rho_s \frac{\partial q}{\partial c}$$

$$D_{\text{eff}} (25 \text{ } ^\circ\text{C}) = 2.58 \pm 0.67 \times 10^{-10} \text{ cm}^2/\text{s}$$

$$D_{\text{eff}} (40 \text{ } ^\circ\text{C}) = 3.69 \pm 0.21 \times 10^{-10} \text{ cm}^2/\text{s}$$

3. Communication & Control

Remotely controlled toys



Remotely controlled chemistry

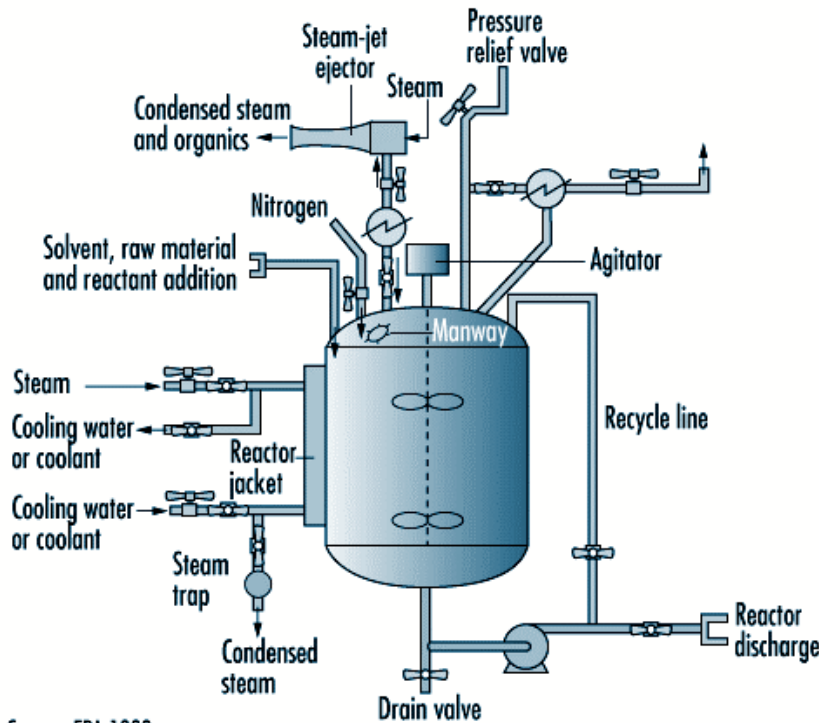


3. Communication & Control



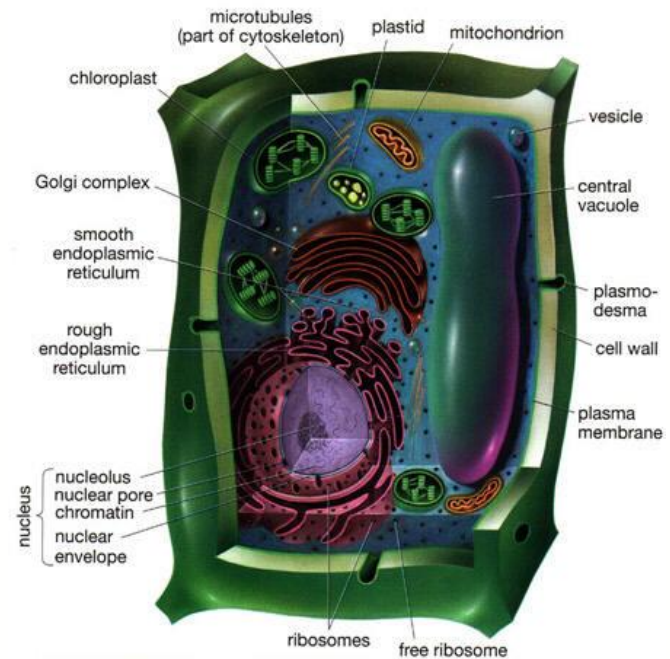
$$r_A = -k(T)c_A = -k_\infty \exp\left(\frac{-E_a}{RT}\right)c_A$$

↙ Presence of a catalyst
← Reactant concentration
↘ Temperature



Source: EPA 1993.

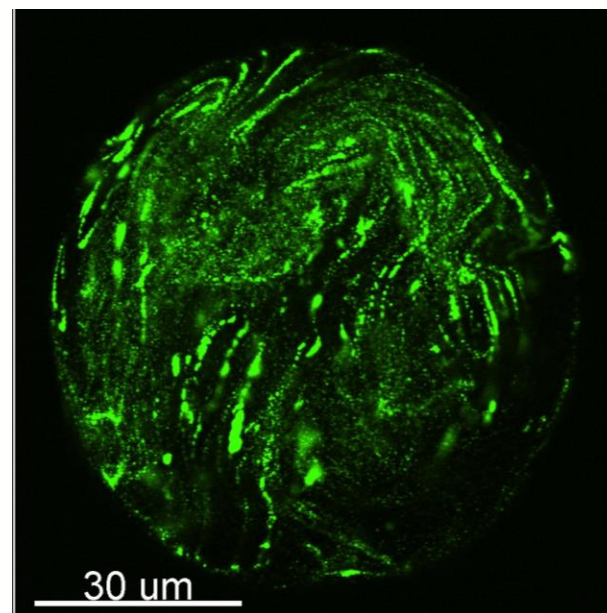
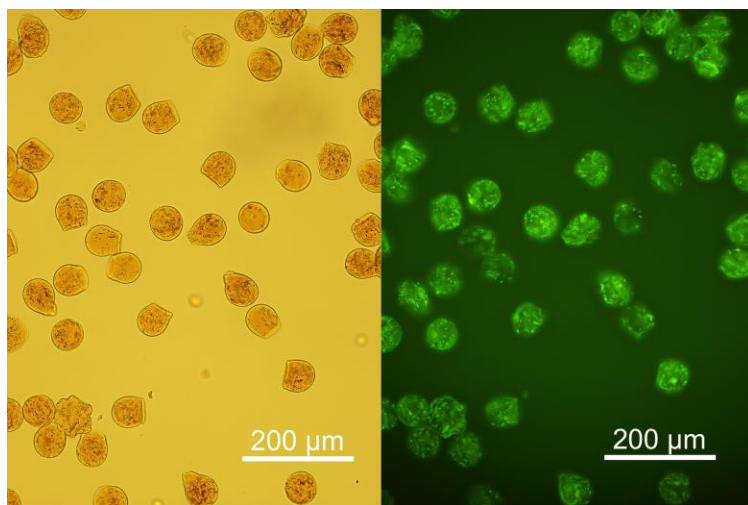
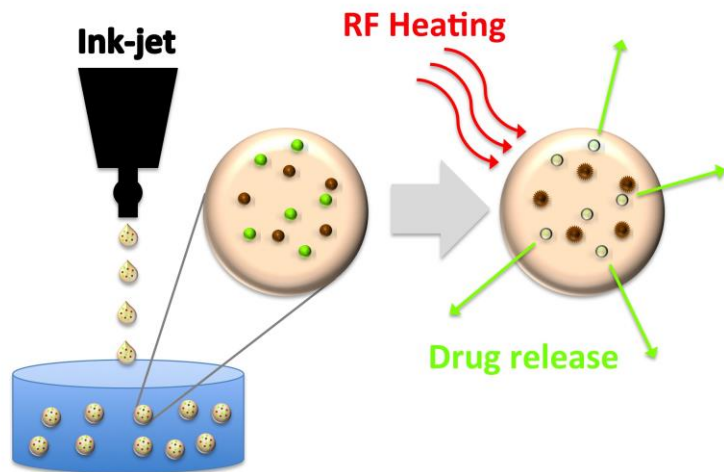
Chemical reactor



BIOLOGY: Life on Earth, Fifth Edition
 by Teresa Audesirk and Gerald Audesirk
 © 1999 by Prentice-Hall, Inc.
 A Simon & Schuster/Viacom Company
 Upper Saddle River, New Jersey 07458

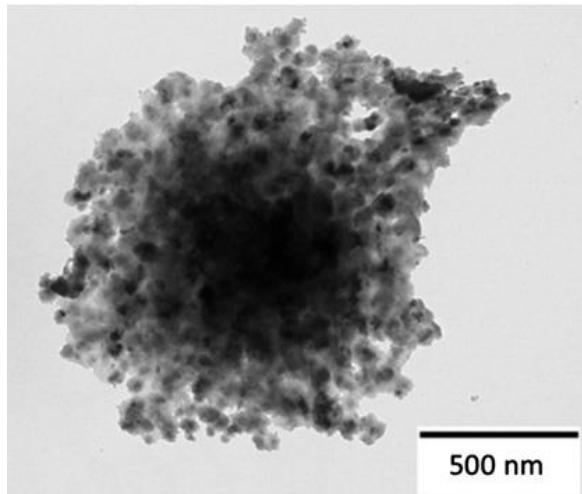
Cell

3. Communication & Control

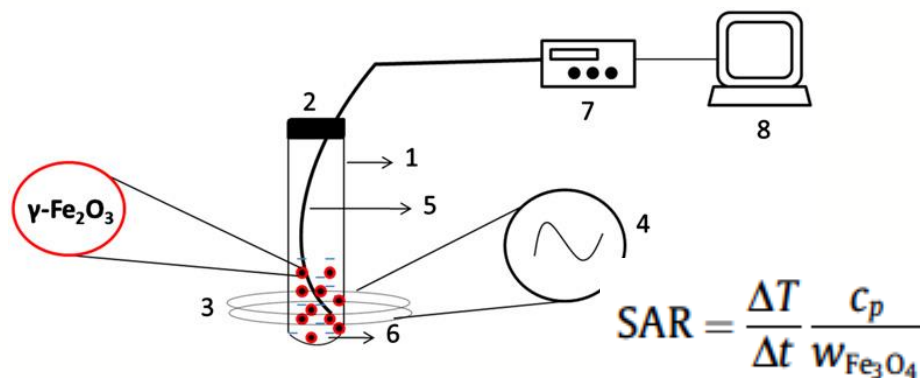


J. Coll. Interf. Sci. **394** (2012) 380-385
Coll. Surf A **410** (2012) 52-57
Langmuir **29** (2013) 4381-4387

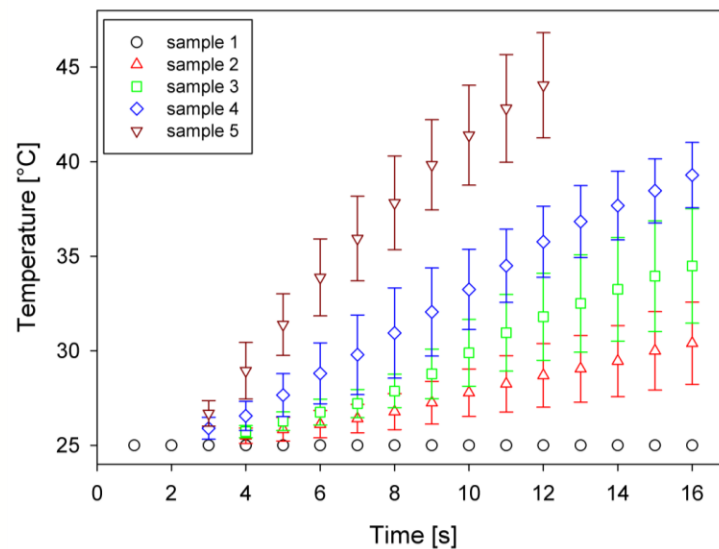
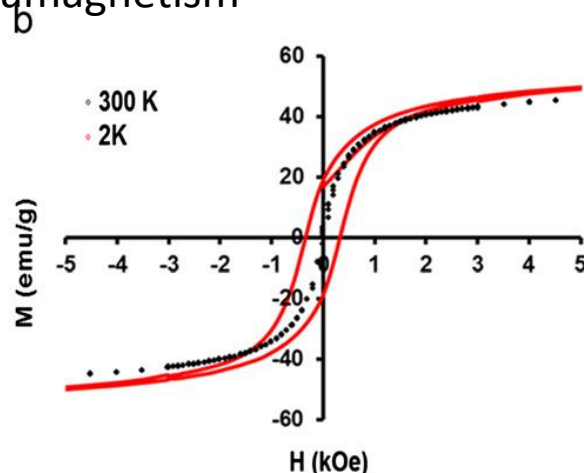
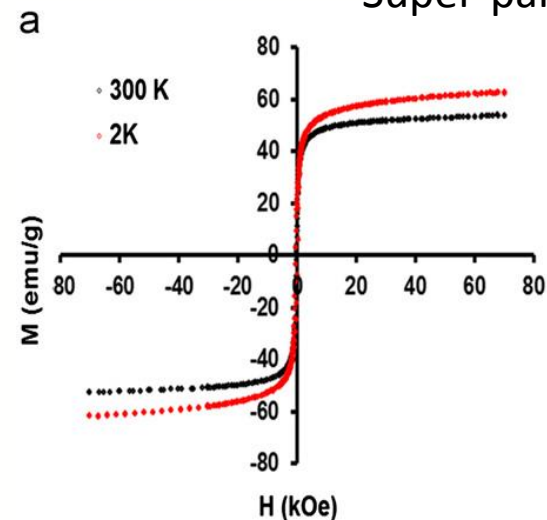
3. Communication & Control



20 mT, 400 kHz, 2.5 kW RF coil
(CEIA PowerCube 32/400)

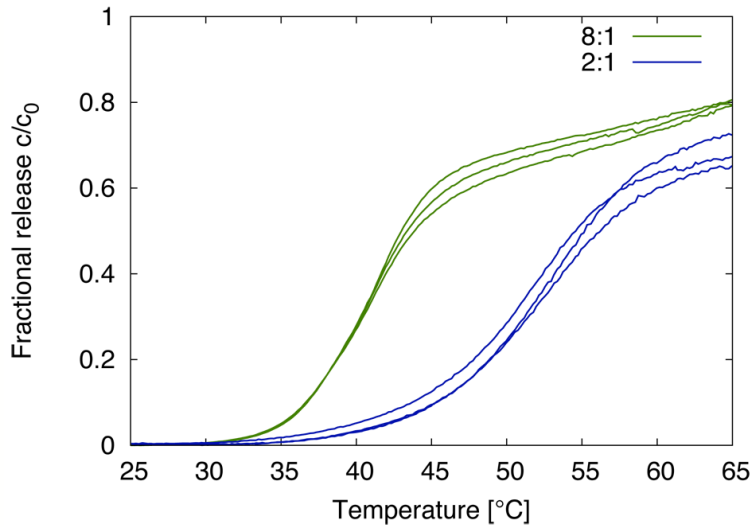


Super-paramagnetism

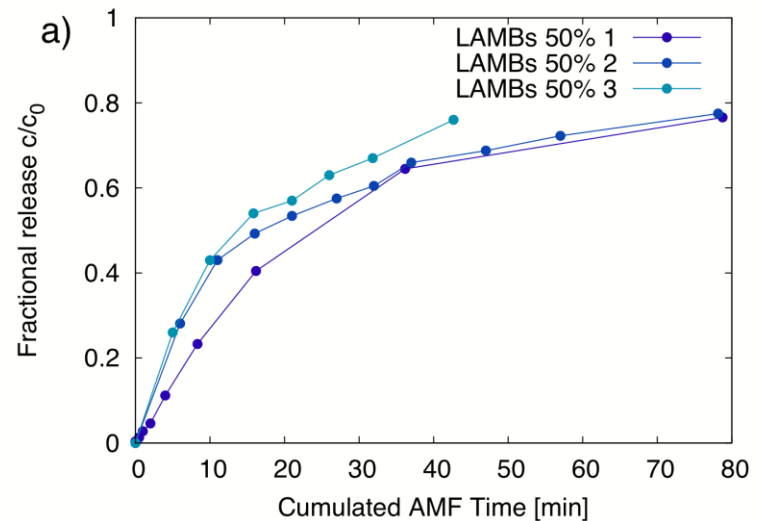
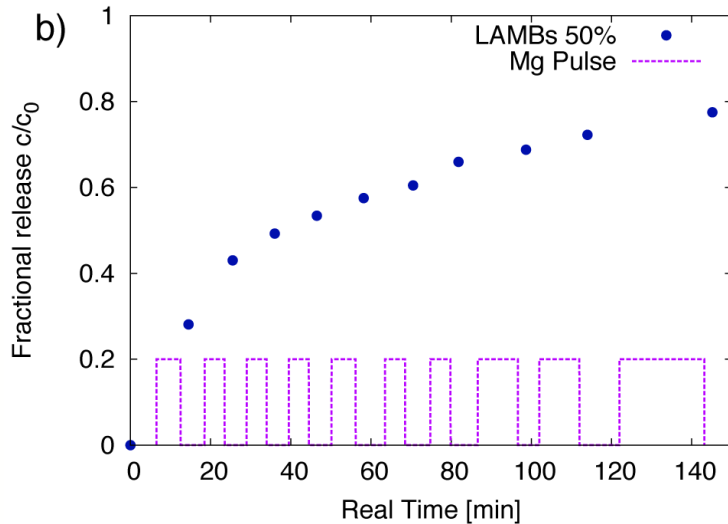
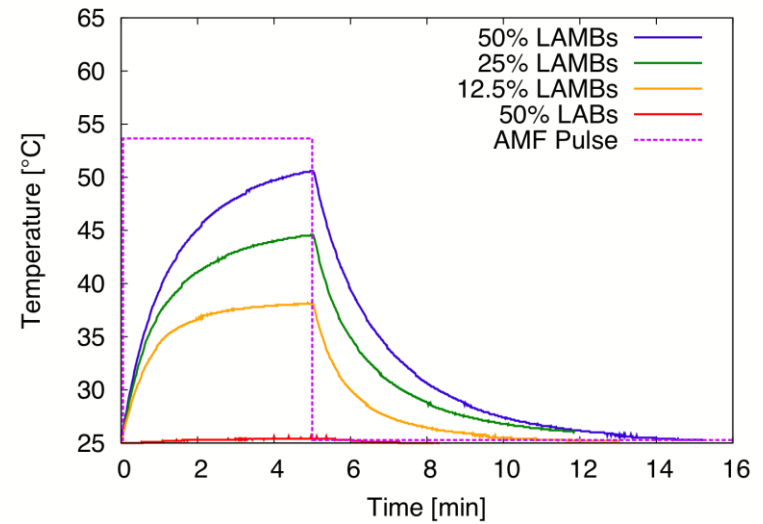


3. Communication & Control

Effect of DPPC:cholesterol ratio

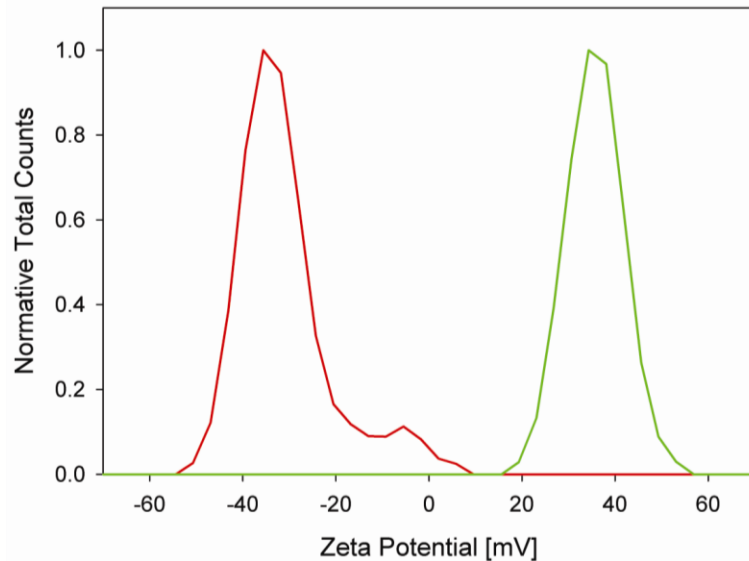


Effect of particle concentration



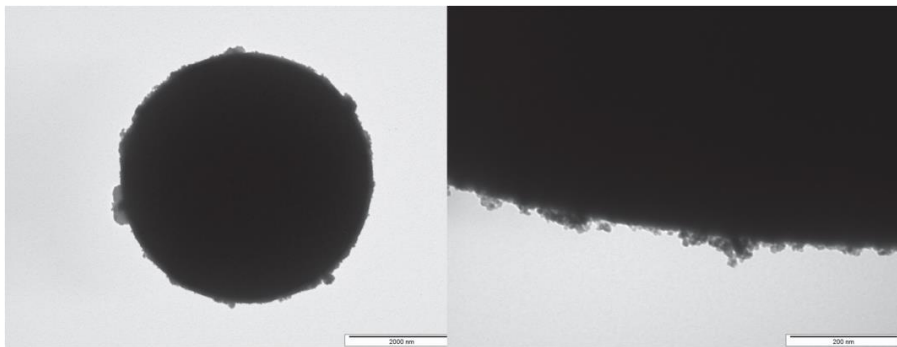
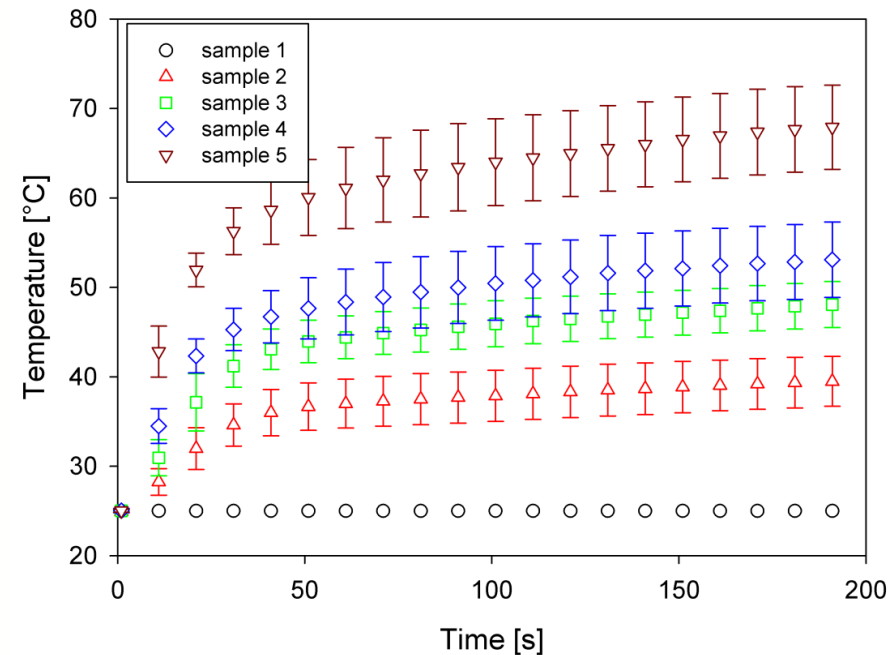
3b. Communication & Control

Iron oxide – silica composites



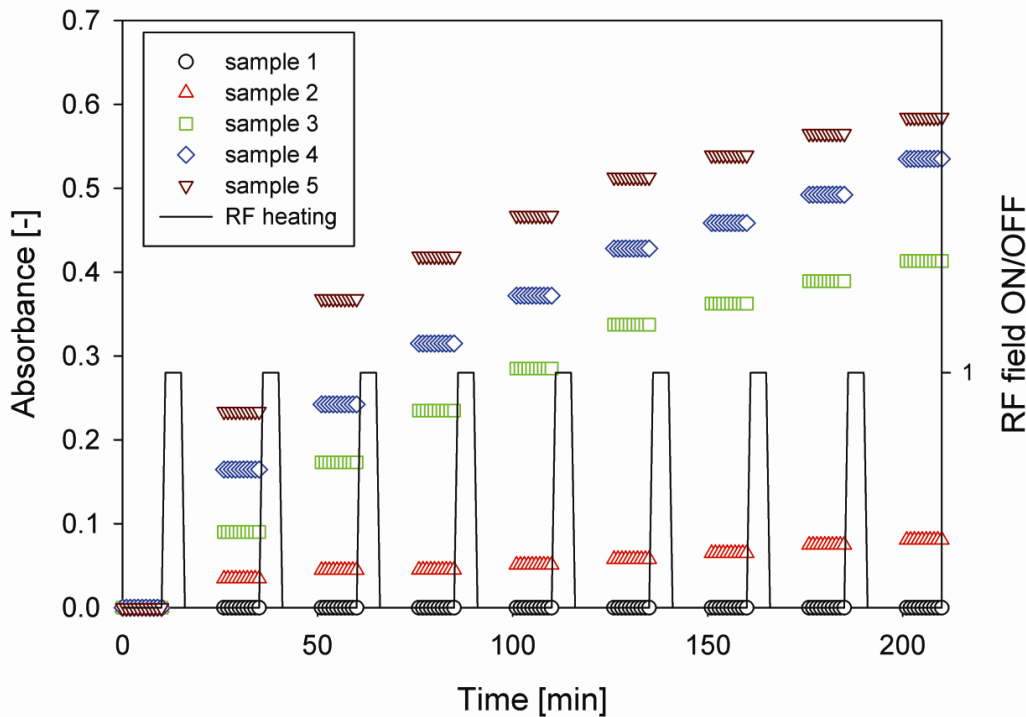
Sample no.	Silica:iron oxide ratio (w/w)
1	1 : 0.0
2	1 : 0.1
3	1 : 0.2
4	1 : 0.4
5	1 : 0.8

Radiofrequency heating

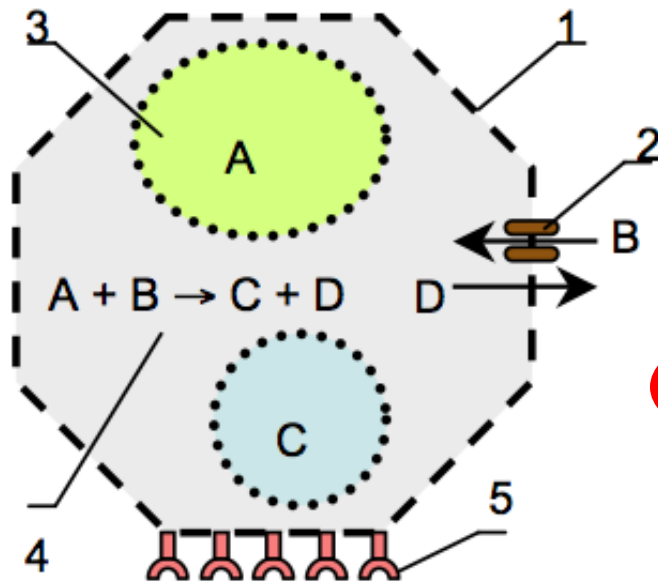


3b. Communication & Control

Radiofrequency controlled diffusion “on demand”



Design of a chemical microrobot

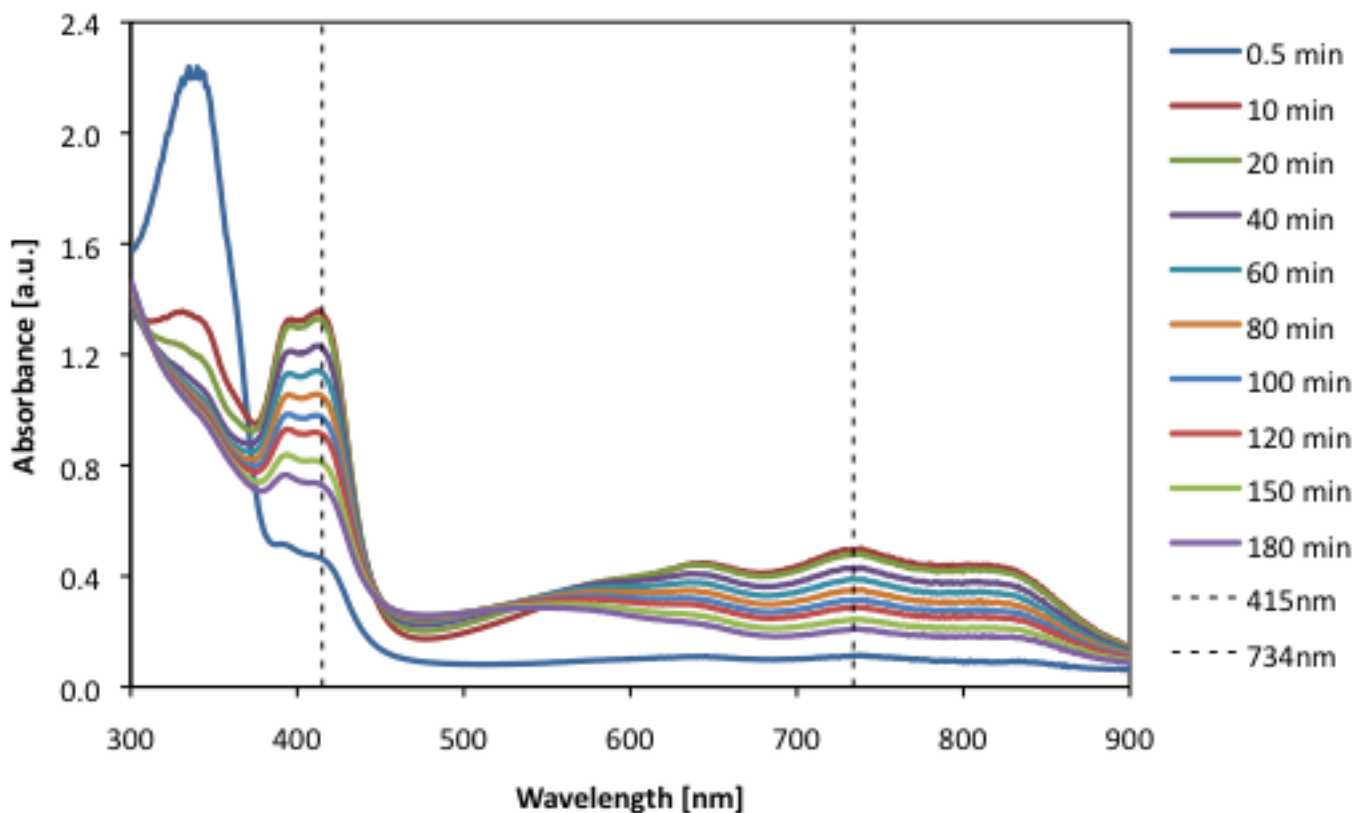
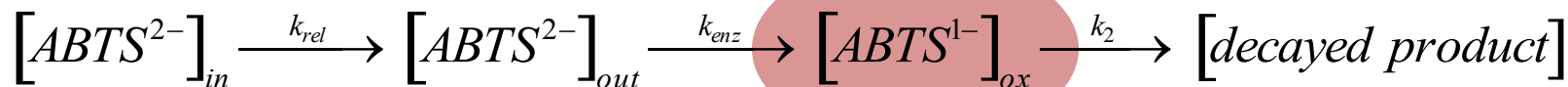


Structural and functional sub-systems:

1. Semi-permeable shell (**integrity**)
2. Variable diffusion rate (**transport**)
3. Internal reservoirs (**storage**)
4. Chemical **reaction** "on-demand"
5. Surface functionalisation (**adhesion**)
6. Remote control (**communication**)

4. Reaction kinetics

In-situ enzymatic production of an unstable active from stable precursor



4. Reaction kinetics

$$\frac{dc_{in}}{dt} = -k_1 c_{in}$$

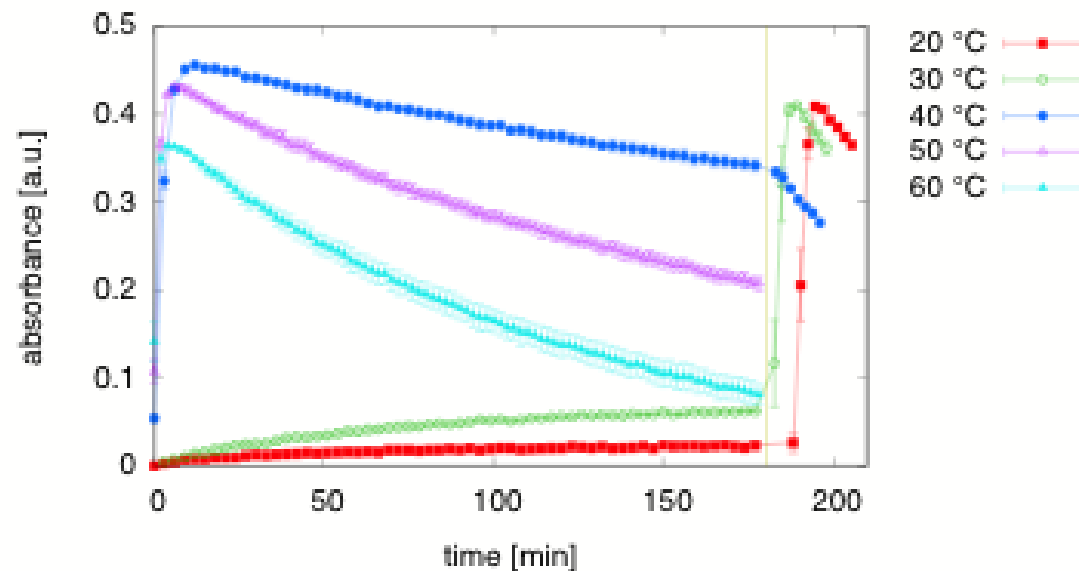
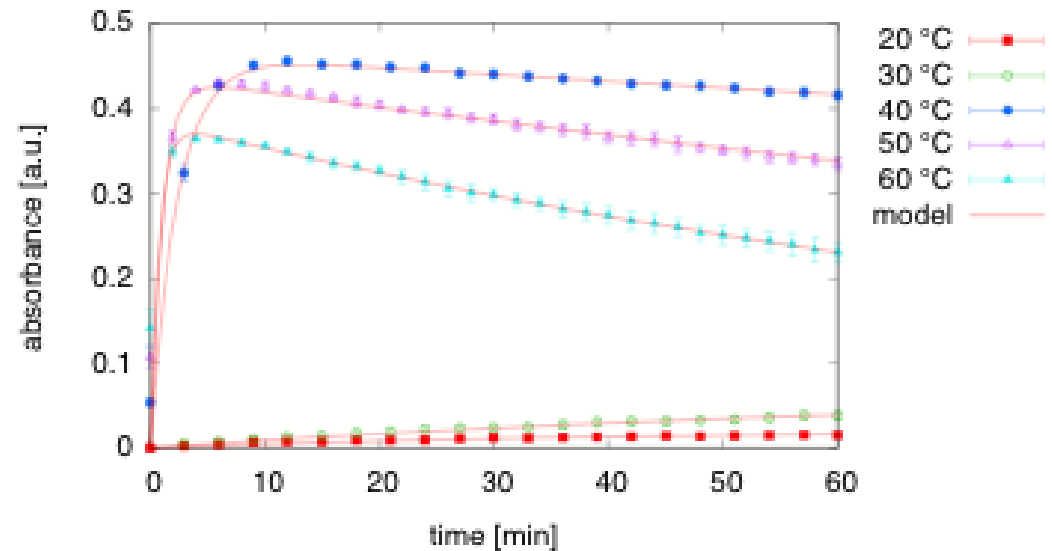
$$\frac{dc_{ox}}{dt} = -k_2 c_{ox} + k_1 c_{in}$$

Sigmoidal dependence on T

$$k_1 = k_m \frac{1}{1 + \exp(-b(T - T_m))}$$

Arrhenius law

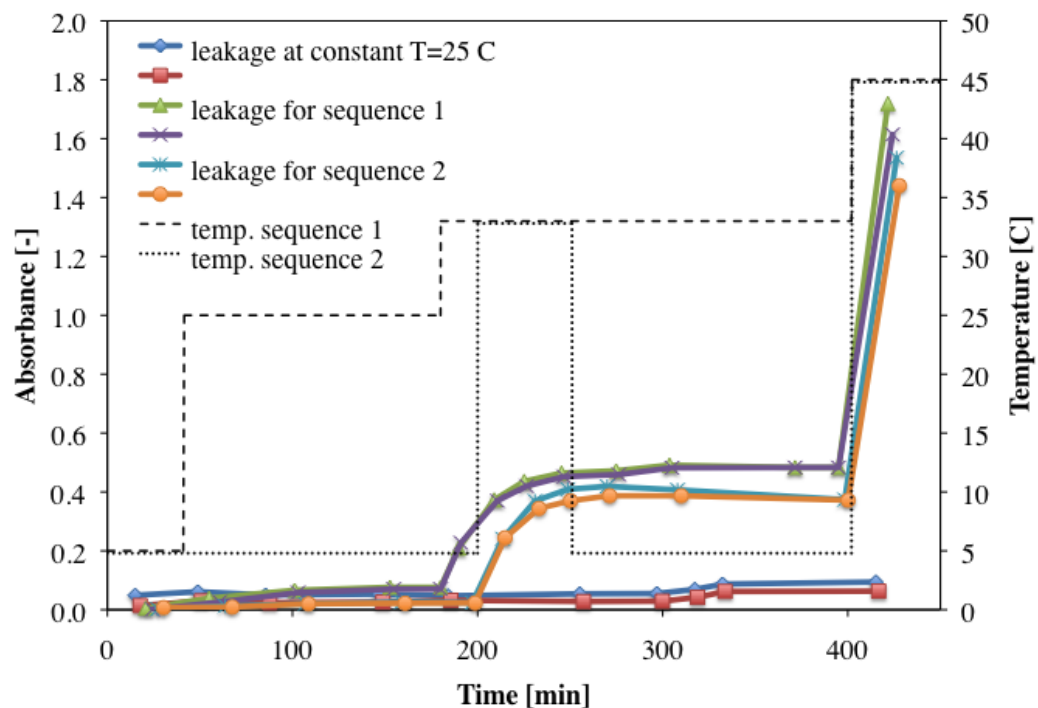
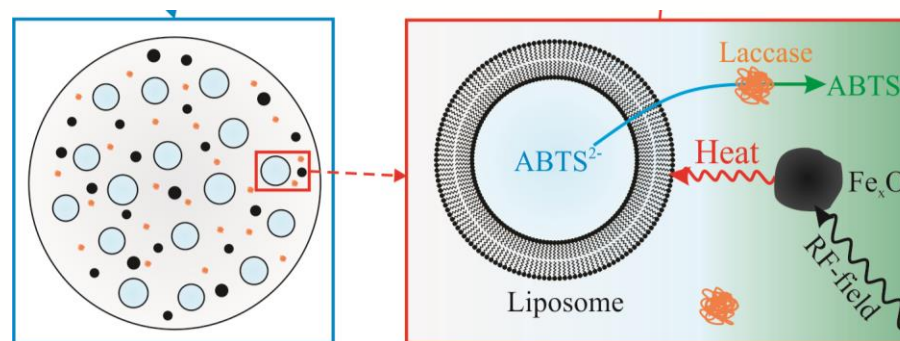
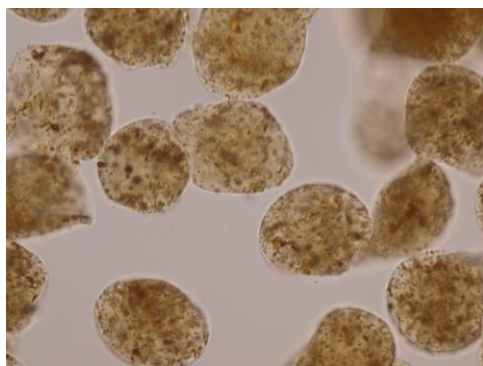
$$\ln k_2 = \frac{A}{T} + B$$



4. Reaction kinetics

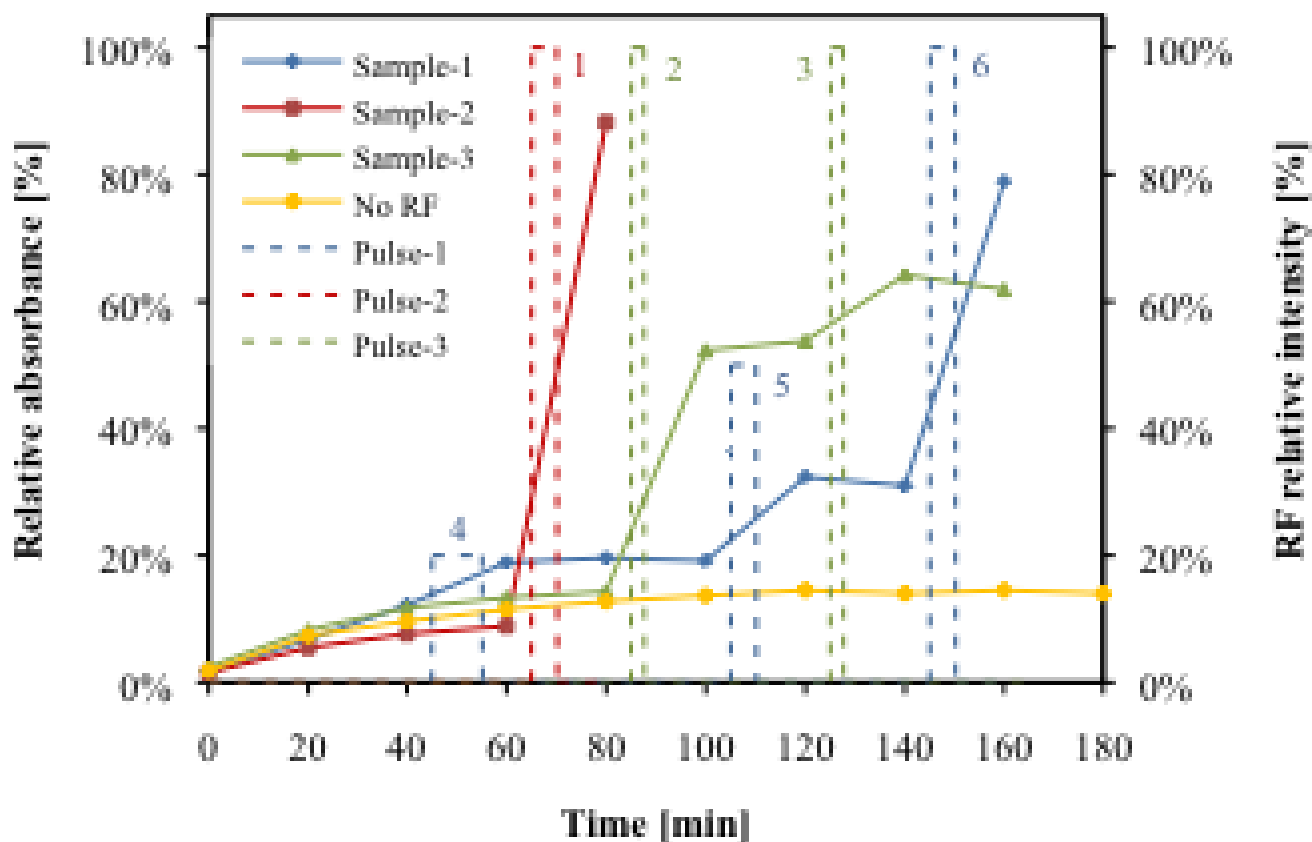


Enzyme: laccase
Substrate: ABTS



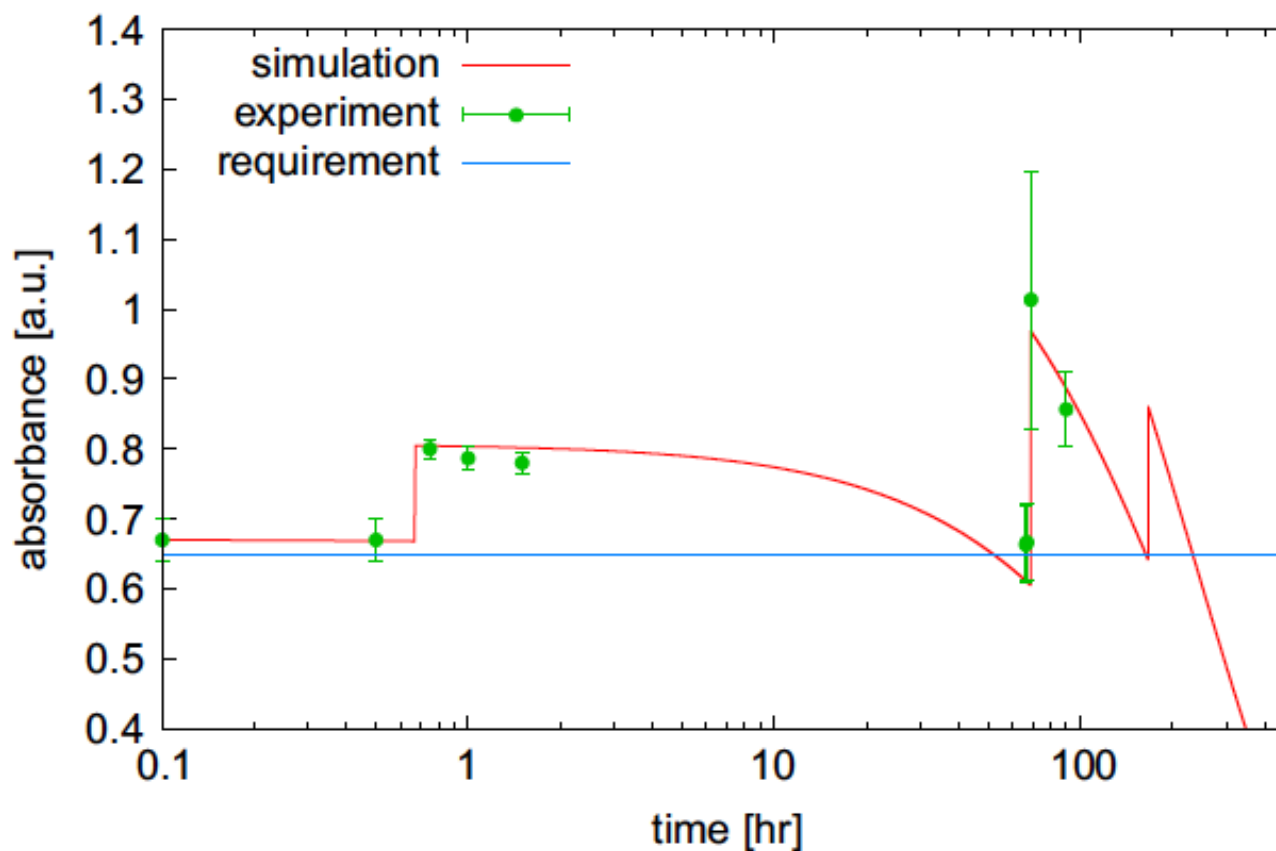
4. Reaction kinetics

Radiofrequency pulse sequences to control production rate of active

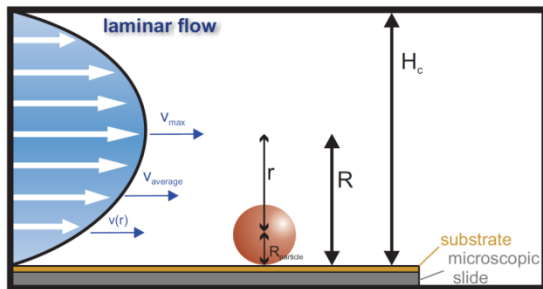
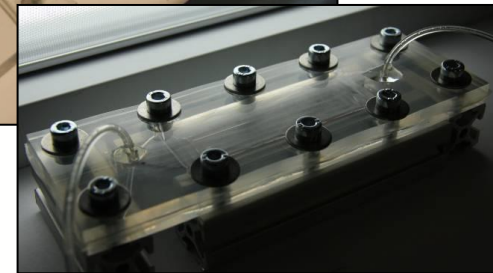
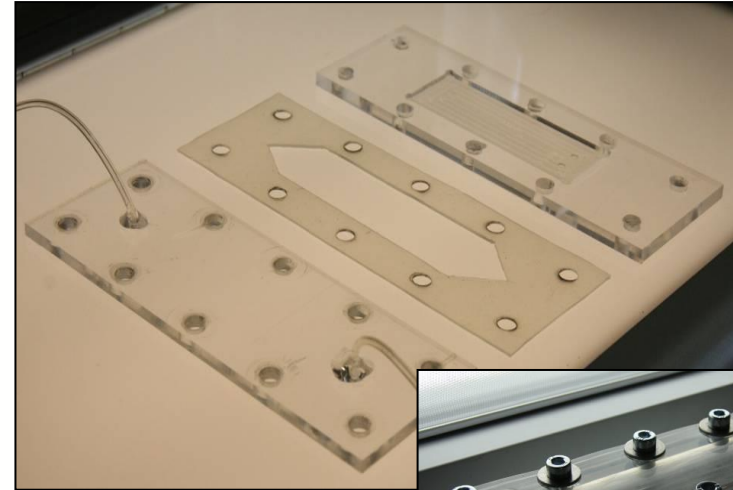
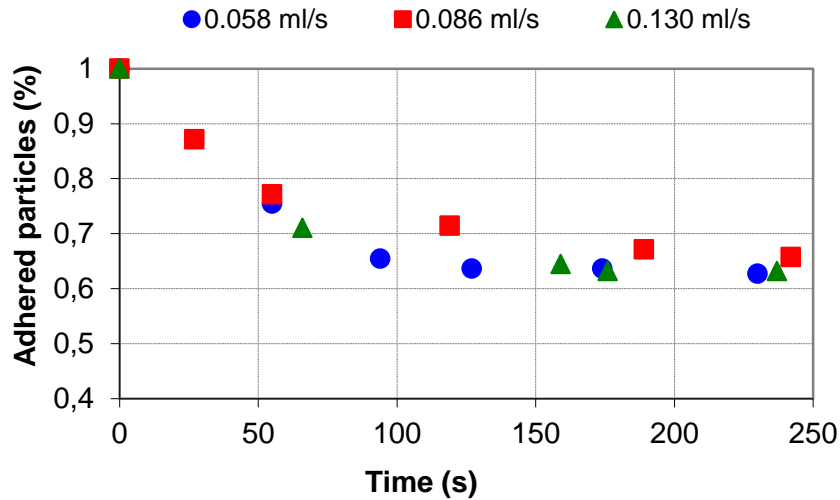


4. Reaction kinetics

Model-predictive control to maintain active concentration above threshold



5. Control of particle adhesion

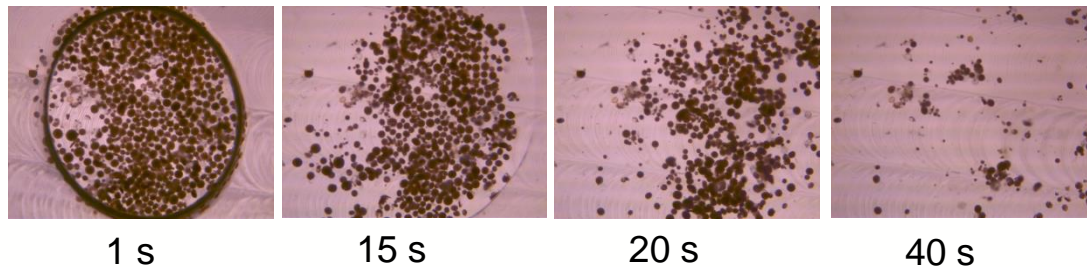
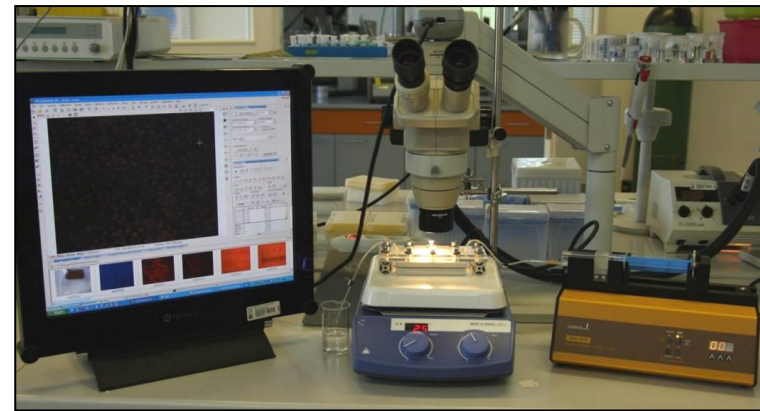


Saffman lift force:

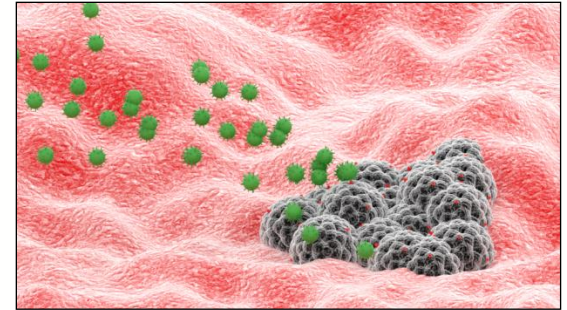
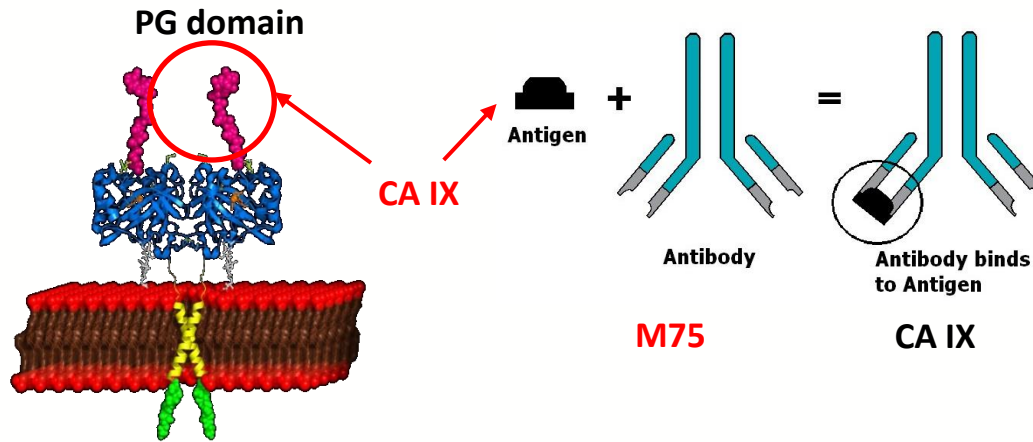
$$F_{lift} = 81.2 \sqrt{\rho_w \mu_w \gamma_0^3} R_{particle}^3$$

Stokes drag force:

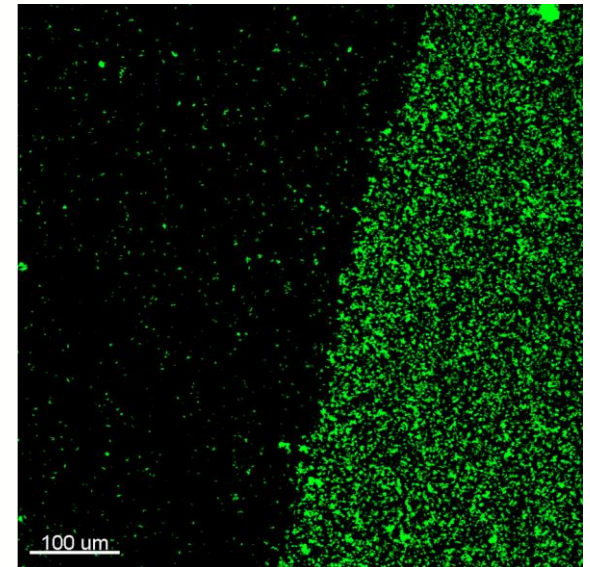
$$F_{drag} = 6\pi R_{particle} v(r)$$



5. Control of particle adhesion



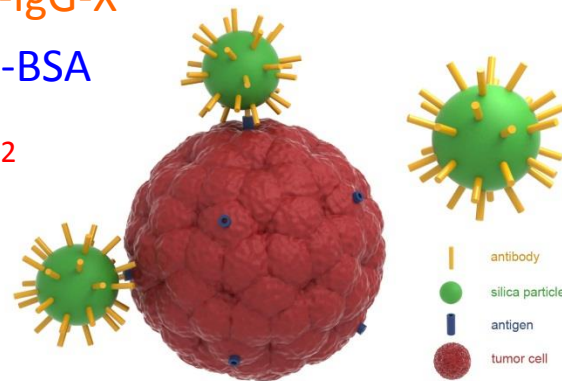
- **antigen CA IX** (carbonic anhydrase 9)
 - transmembrane protein
 - expressed in cancers (lung, colon, breast, cervix, ovaries, brain, oral cavity...)
- **antibody M75**
 - recognizes unique PG domain of CA IX



5. Control of particle adhesion

- 4 types of particles:

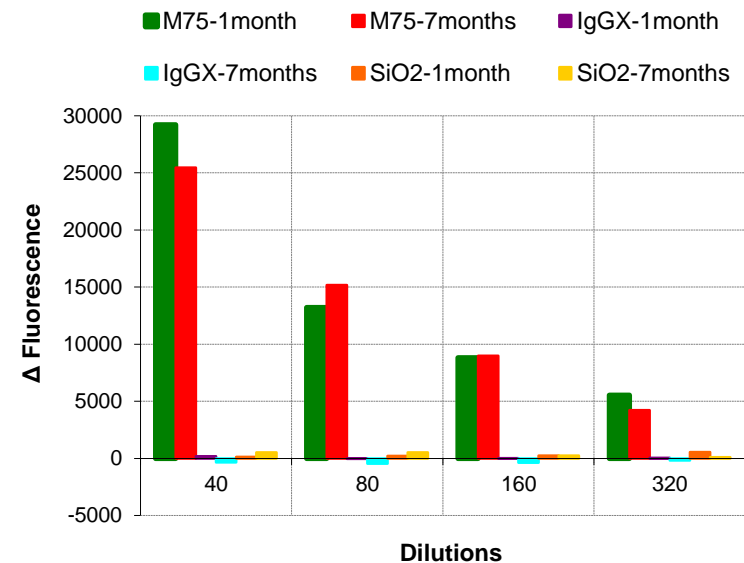
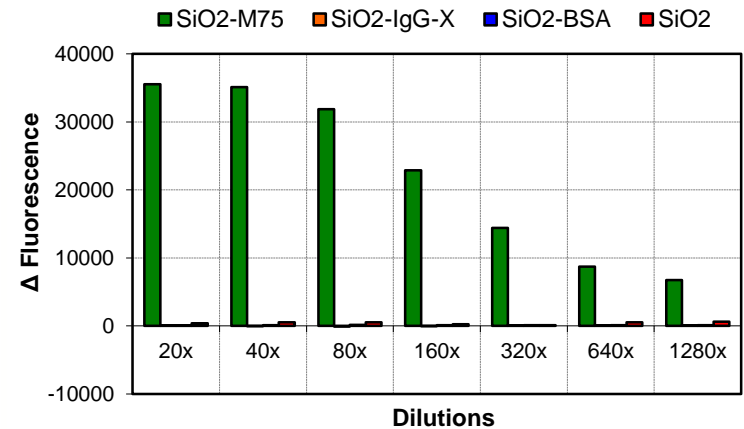
- specific : $\text{SiO}_2\text{-M75}$
- unspecific: $\text{SiO}_2\text{-IgG-X}$
- $\text{SiO}_2\text{-BSA}$
- unmodified: SiO_2



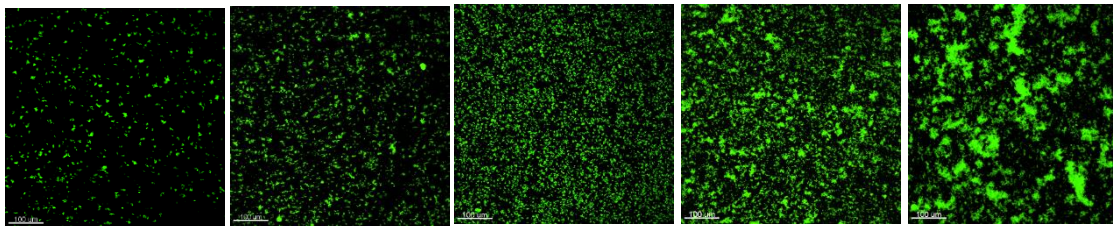
- covalent coupling of proteins and antibodies to obtain monolayer

- ELISA - *enzyme-linked immunosorbent assay* - spectrophotometric detection of specific protein (antibody)

- ELISA-like* – no need of secondary antibody for detection

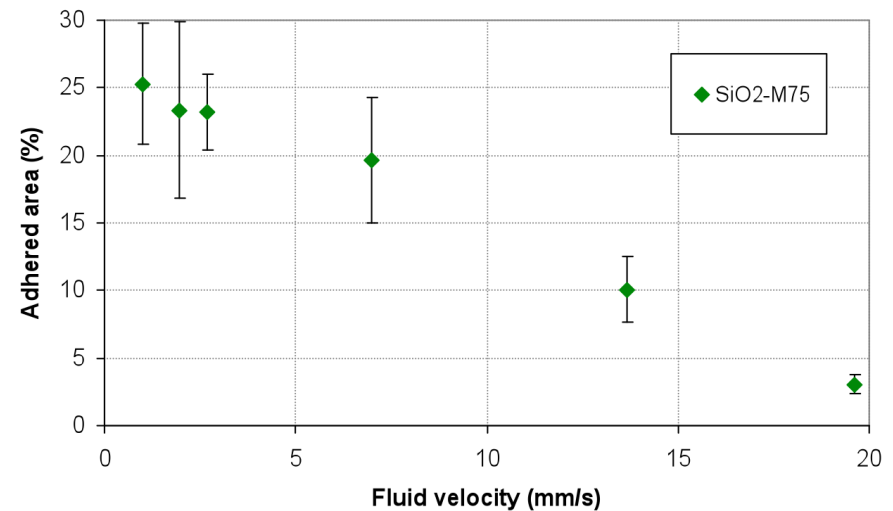
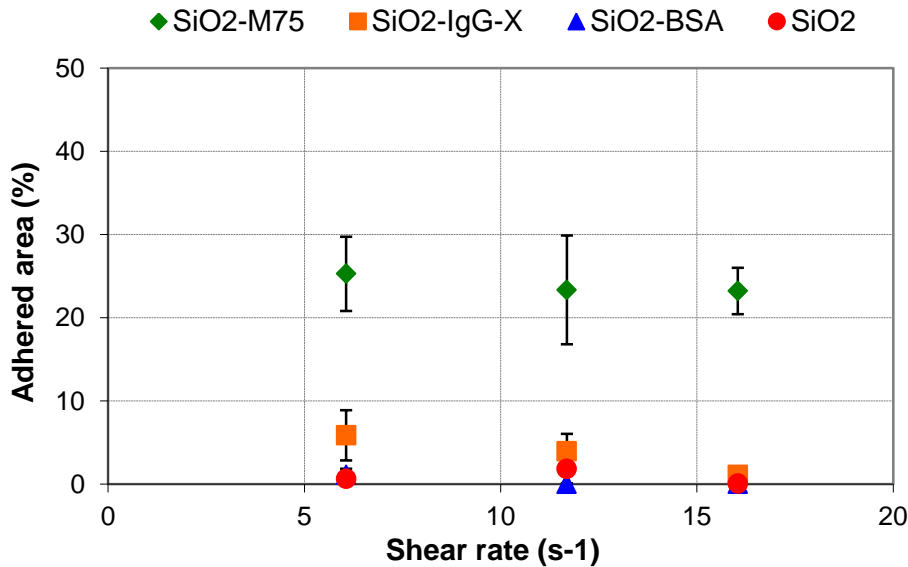
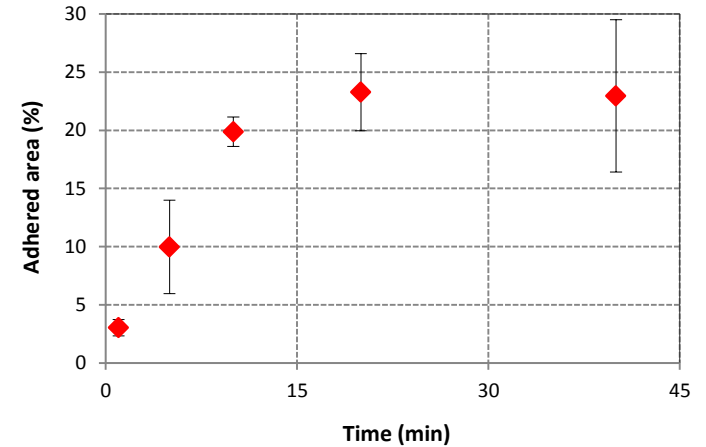


5. Control of particle adhesion



1min 5min 10min 20min 40min

- increasing exposure time of SiO_2 -M75 with PG-MBP modified plastic slides

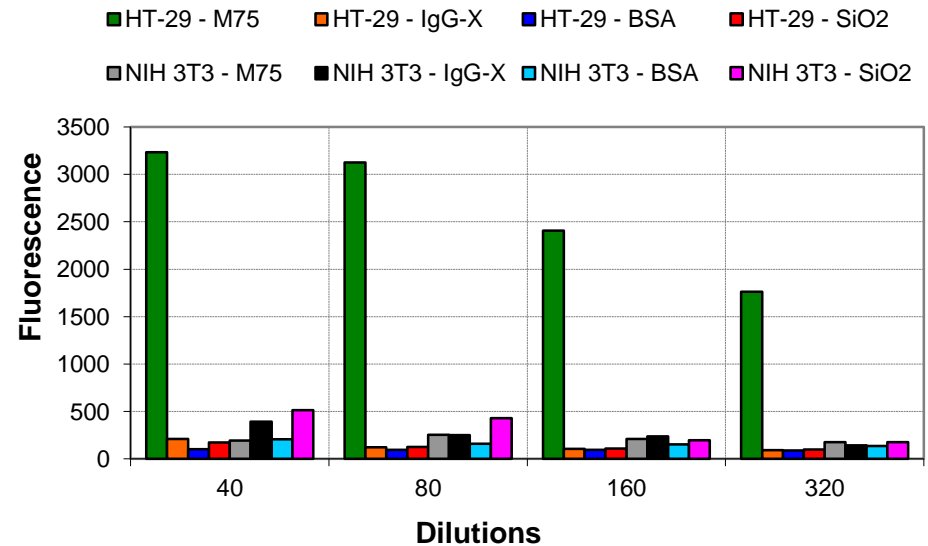
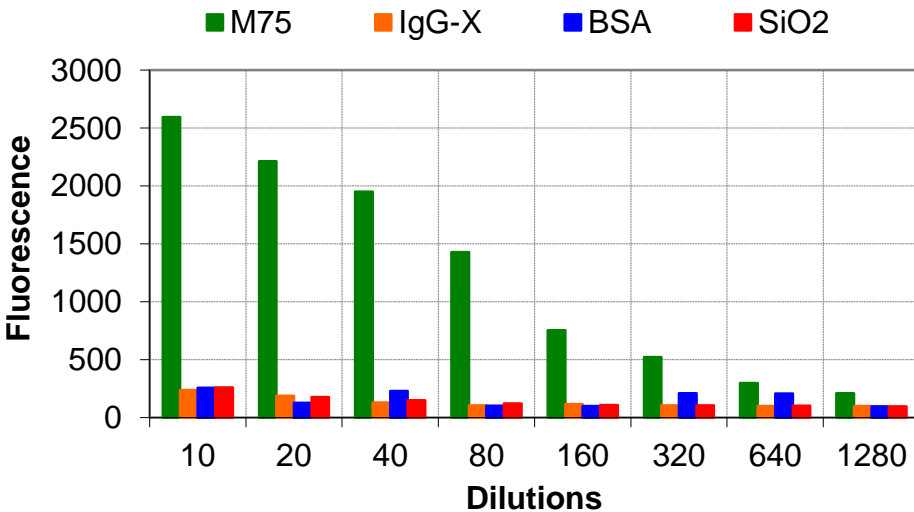
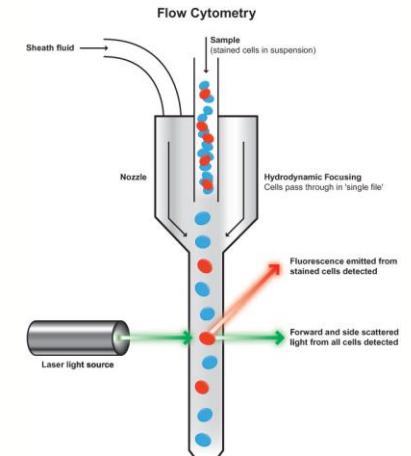
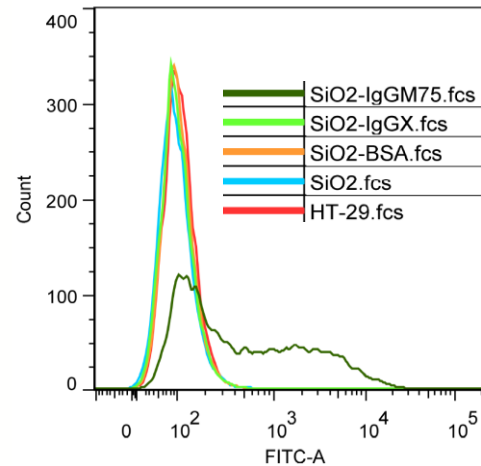


5. Control of particle adhesion

HT-29 cell line (derived from colorectal carcinoma) expressed antigen CA IX which binds with M75-modified particles

NIH 3T3 (embryonic fibroblast cell line)

- no expression of CA IX on surface
- negative control



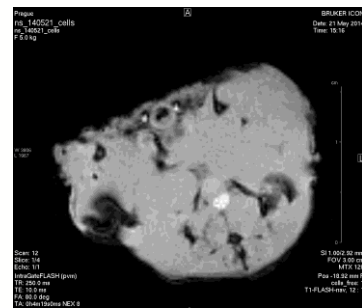
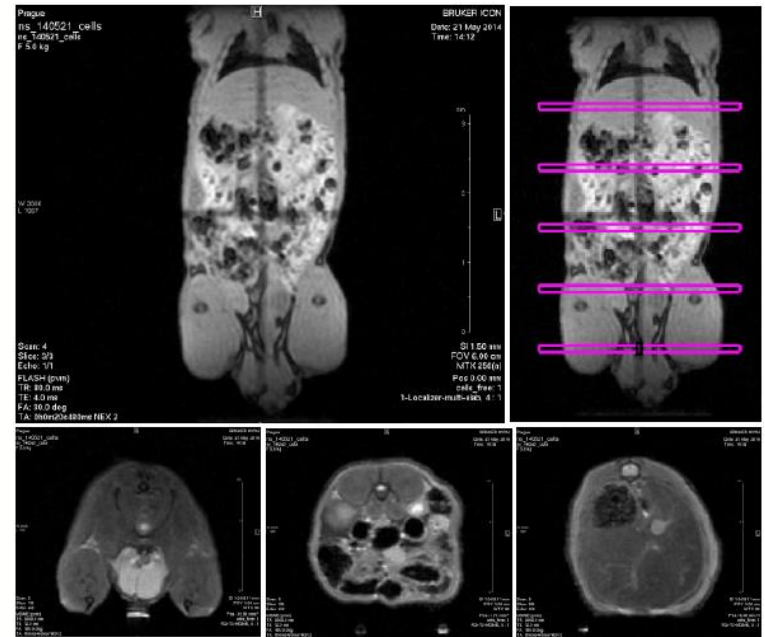
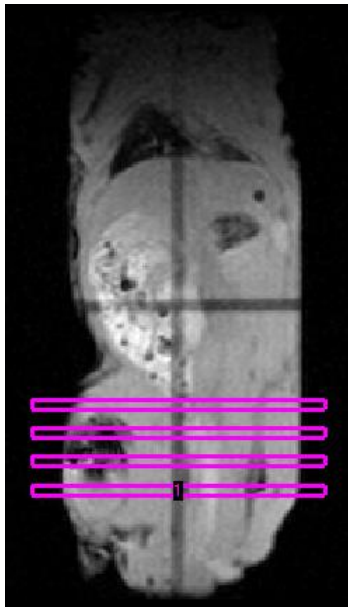
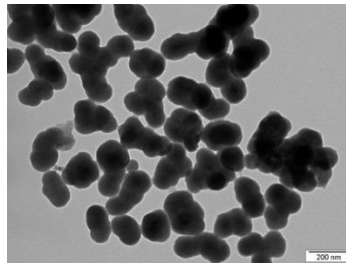
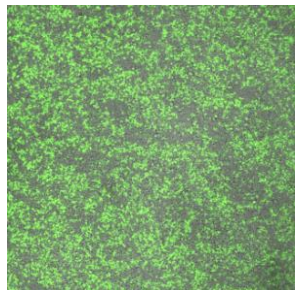
5. Control of particle adhesion

On-going work: *in vivo* studies

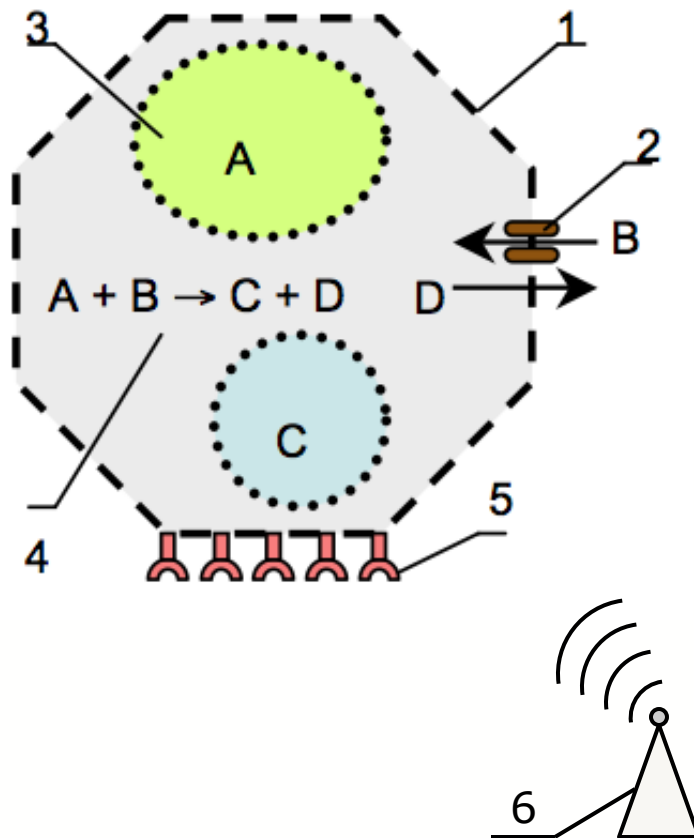
NU/NU nude mice

Human carcinoma HT-29

Multi-modal imaging (MRI & Fluorescence)



Design of a chemical microrobot

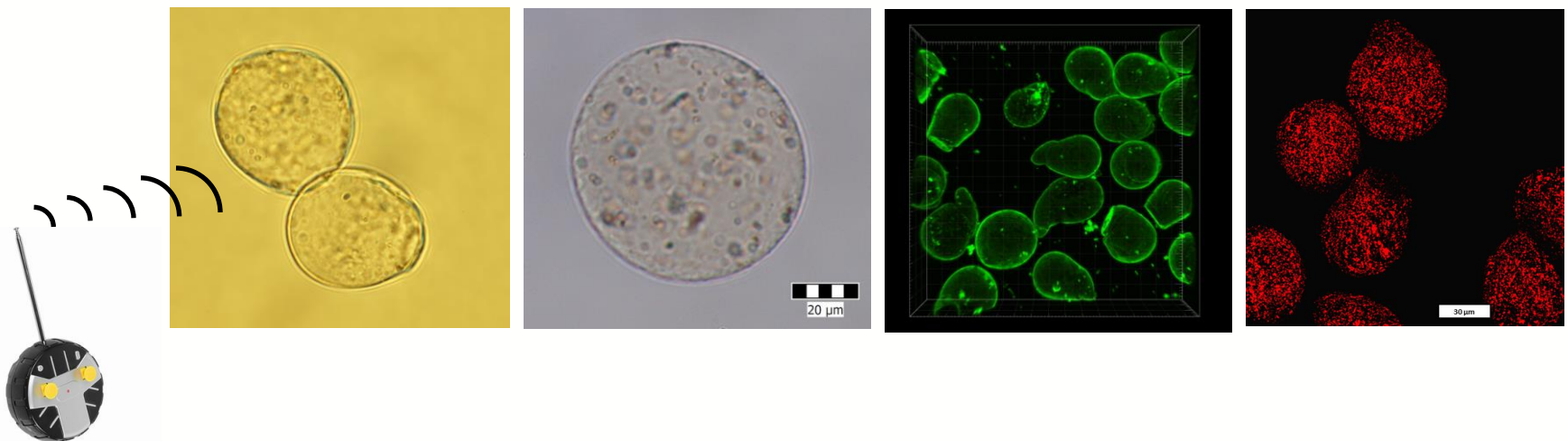


Structural and functional sub-systems:

1. Semi-permeable shell (**integrity**)
2. Variable diffusion rate (**transport**)
3. Internal reservoirs (**storage**)
4. Chemical **reaction** "on-demand"
5. Surface functionalisation (**adhesion**)
6. Remote control (**communication**)

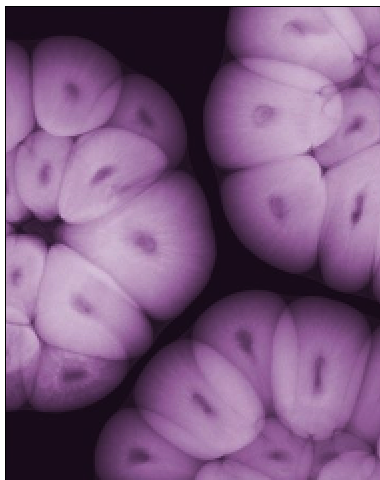
Conclusions

- Multi-compartment particles - “chemical robots”
- Remotely controlled diffusion by RF signals
- Control of enzymatic reaction
- Control of adhesion via antigen-antibody interaction

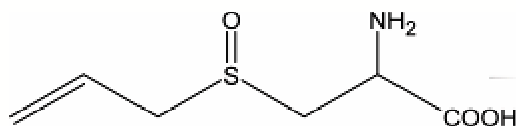


Applications

- 1) Cancer theragnostics (MRI imaging + RF triggered drug release)
- 2) Delivery of natural fungicides (crop protection)
- 3) Delivery of unstable natural antibiotics - allicin

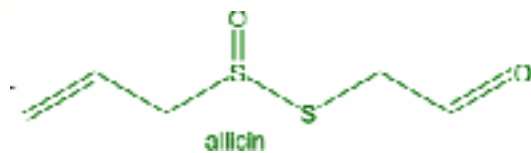


Garlic bulb
(*Allium sativum*)



Aliin (stable precursor)

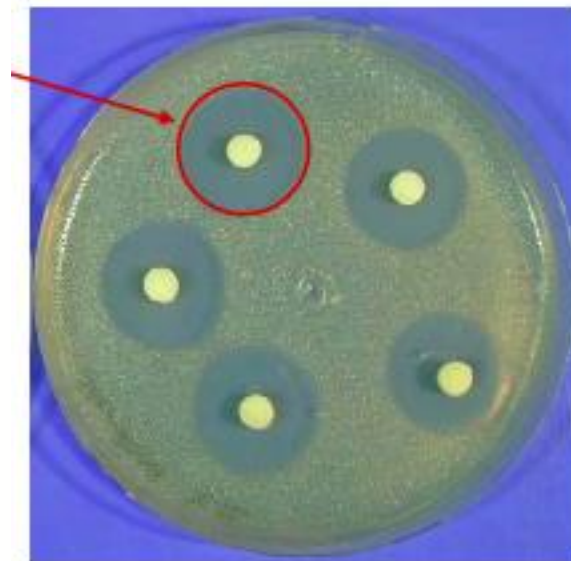
Enzyme allinase



Allicin (bactericidal but unstable)

Inhibition
zones

E. coli DH5α



Thank you



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Jiří Dohnal
Michaela Gajdošová
Zdeněk Grof
Jaroslav Hanuš
Petra Haufová
Jan Holaň
Martin Jakubec
Ondřej Kašpar
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Martin Ullrich
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Aleš Zadražil
Zhao Zhou